

Construction of geometric  
cone-manifold structures with  
prescribed holonomy

Daniel V. Mathews

19 January 2006

## Geometric structures and holonomy

Recall a geometric  $(X, \text{Isom } X)$  structure on a manifold  $M$  is a metric on  $M$  locally isometric to  $X$ .

A geometric  $(X, \text{Isom } X)$  structure on a manifold  $M$  gives a local isometry with  $X$  which extends to a *developing map*  $\mathcal{D} : \tilde{M} \longrightarrow X$ .

For each  $\alpha \in \pi_1(M)$ , the developing map gives a path in  $X$ . The start and end points are related by an isometry  $\rho(\alpha)$ .

The map  $\rho : \pi_1(M) \longrightarrow \text{Isom } X$  so obtained is a homomorphism and is called the *holonomy*.

A geometric *cone manifold* structure determines a holonomy map  $\rho : \pi_1(M) \longrightarrow \text{Isom } X$  if all interior cone angles are multiples of  $2\pi$ .

## The problem

Given a homomorphism  $\rho : \pi_1(M) \longrightarrow \text{Isom } X$ ,  
is  $\rho$  the holonomy of some structure on  $M$ ?

- geometric structure on  $M$ ?
- geometric cone-manifold structure with interior cone angles multiples of  $2\pi$ ?
- if  $M$  has boundary, with totally geodesic boundary? With corners? Allowing too many corners trivialises the problem.

## Some known answers.

- (i) Leleu 2000: 3-dimensional hyperbolic, Euclidean, spherical manifolds with nonempty (non-geodesic) boundary.

$\rho : \pi_1(M) \longrightarrow \text{Isom } X$  is the holonomy of a geometric structure if and only if  $\rho$  lifts to  $\tilde{\rho} : \pi_1(M) \longrightarrow \widetilde{\text{Isom } X}$ .

No control on boundary.

- (ii) Gallo, Kapovich, Marden 2000: closed surfaces with complex projective structures.

Any nonelementary  $\rho : \pi_1(S) \longrightarrow PSL_2\mathbb{C}$  is the holonomy of a complex projective cone manifold structure. No cone points are required iff  $\rho$  lifts to  $SL_2\mathbb{C}$ . Otherwise a single  $4\pi$  cone point is required.

## 2-dimensional hyperbolic geometry

**Theorem 1 (Goldman 1988)** *For a closed surface  $S$ ,  $\chi(S) < 0$ , the Euler class  $\mathcal{E}(\rho)$  classifies the topological components of the algebraic variety of representations  $\rho : \pi_1(S) \longrightarrow PSL_2\mathbb{R}$ .*

The Euler class  $\mathcal{E}(\rho) \in H^2(S)$  and

$$\chi(S) \leq \mathcal{E}(\rho)[S] \leq -\chi(S).$$

**Theorem 2 (Goldman 1980)** *For a closed surface  $S$ ,  $\chi(S) < 0$ , the representations with  $\mathcal{E}(\rho)[S] = \pm\chi(S)$  are precisely the holonomy representations of (non-singular) hyperbolic structures on  $S$ .*

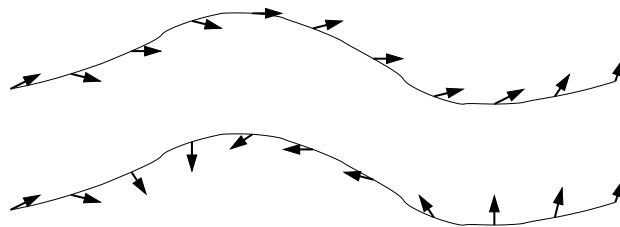
I.e. the holonomy representations are those “least liftable” to  $PSL_2\mathbb{R}$ .

## The Euler class of a representation

Most useful description in terms of  $\widetilde{PSL}_2\mathbb{R} \cong \widetilde{UT\mathbb{H}^2} \cong \mathbb{H}^2 \times S^1 \cong \mathbb{H}^2 \times \mathbb{R}$ .

Elements of  $\widetilde{PSL}_2\mathbb{R}$  are homotopy classes of paths in  $UT\mathbb{H}^2$ .

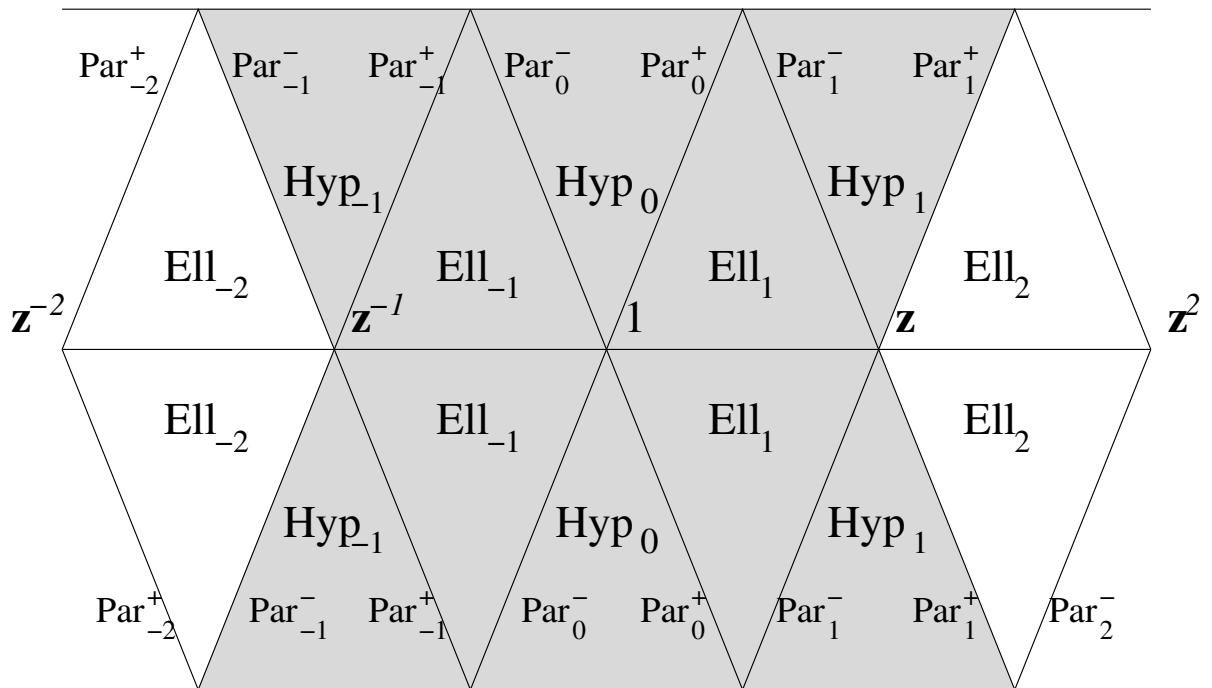
Any  $\alpha \in PSL_2\mathbb{R}$  has infinitely many lifts to  $\widetilde{PSL}_2\mathbb{R}$ . These are paths in  $UT\mathbb{H}^2$  with the same start and end tangent vectors, but differ according to the number of times that the tangent vectors “spin”.



The fibre over  $1 \in PSL_2\mathbb{R}$  is an infinite cyclic group  $\{z^n\}$ .

The lifts of  $\alpha \in PSL_2\mathbb{R}$  are precisely  $z^n\tilde{\alpha}$ .

# Schematic diagram of $\widetilde{PSL}_2\mathbb{R}$



|          |         |         |         |        |     |       |        |        |        |
|----------|---------|---------|---------|--------|-----|-------|--------|--------|--------|
| Tw       | $-4\pi$ | $-3\pi$ | $-2\pi$ | $-\pi$ | $0$ | $\pi$ | $2\pi$ | $3\pi$ | $4\pi$ |
| $\theta$ | $-2\pi$ |         | $-\pi$  |        | $0$ |       | $\pi$  |        | $2\pi$ |
| Tr       | $2$     |         | $-2$    |        | $2$ |       | $-2$   |        | $2$    |

A hyperbolic/parabolic element  $\alpha \in PSL_2\mathbb{R}$  has a *simplest* lift to  $\widetilde{PSL}_2\mathbb{R}$  (“drive straight along the axis”). These form  $\text{Hyp}_0/\text{Par}_0$ . Their *twist* is small.

## Commutators

Commutators are well-defined: if  $\alpha, \beta \in PSL_2\mathbb{R}$  then  $[\alpha, \beta] \in \widetilde{PSL_2\mathbb{R}}$  makes sense.

Commutators are “not too twisty”: lie in the shaded region.

Take presentation for  $\pi_1(S)$ :  
generators  $G_1, H_1, \dots, G_k, H_k, C_1, \dots, C_n$   
relator  $[G_1, H_1] \cdots [G_k, H_k] C_1 \cdots C_n$ .

A representation into  $PSL_2\mathbb{R}$  is equivalent to choice of  $g_i, h_i, c_i \in PSL_2\mathbb{R}$  with

$$[g_1, h_1] \cdots [g_k, h_k] c_1 \cdots c_n = 1.$$

For closed surfaces, this relator is well-defined in  $\widetilde{PSL_2\mathbb{R}}$ . For surfaces with boundary, we may take lifts  $\tilde{c}_i$  with small twist.



## Representations of surface groups: the Milnor-Wood inequality

We have

$$[\tilde{g}_1, \tilde{h}_1] \cdots [\tilde{g}_k, \tilde{h}_k] \tilde{c}_1 \cdots \tilde{c}_n = \mathbf{z}^m$$

for some  $m$ . Since “twist” is approximately additive  $m$  is bounded:

$$\chi(S) \leq m \leq -\chi(S).$$

For a closed surface,  $m$  depends only on  $\rho$  and gives the Euler class of  $\rho$ .  $\mathcal{E}(\rho)[S] = m$ .

For a surface with boundary we may define a *relative Euler class* if we require  $\rho$  to take boundary curves to non-elliptics.

If  $\rho$  is the holonomy of a (non-singular) hyperbolic structure then  $\mathcal{E}(\rho)[S] = \pm\chi(S)$ .

For a closed surface, every step towards 0 requires an extra  $2\pi$  worth of cone angle.

### **Punctured torus theorem:**

Let  $S$  be a punctured torus. A representation  $\rho$  is the holonomy of a hyperbolic cone-manifold structure with at most one corner point and no interior cone points if and only if  $\rho$  is not virtually abelian.

### **Genus 2 surface theorem:**

Let  $S$  be a genus 2 closed surface. Let  $\rho$  be a representation with

- (i)  $\mathcal{E}(\rho)[S] = \pm 1$  (i.e. one off extremal).
- (ii) for some separating curve  $C$ ,  $\rho(C)$  is not hyperbolic.

Then  $\rho$  is the holonomy of a hyperbolic cone-manifold structure with one  $4\pi$ -angle cone point.

**“Almost every” theorem:**

Let  $S$  be a closed orientable surface,  $\chi(S) < 0$ . Almost every representation  $\rho : \pi_1(S) \longrightarrow PSL_2\mathbb{R}$  such that

- (i)  $\mathcal{E}(\rho)[S] = \pm(\chi(S) + 1)$  (i.e. “one off maximal”), and
- (ii)  $\rho$  sends some non-separating simple closed curve to an elliptic,

is the holonomy of a hyperbolic cone-manifold structure on  $S$  with a single cone point with cone angle  $4\pi$ .

## The relevant measure

Goldman (1984) constructed a measure on the character variety  $X(S)$  of representations  $\rho : \pi_1(S) \longrightarrow PSL_2\mathbb{R}$ . (“Representations up to conjugacy.”)

The tangent space of  $X(S)$  at  $[\rho_0]$  is

$$H^1(\pi_1(S); \mathfrak{sl}_2\mathbb{R}_{\text{Ad}\rho_0})$$

( $\mathfrak{sl}_2\mathbb{R}$  as a  $\pi_1(S)$ -module via  $\rho_0$  and the adjoint representation).

The cup product and the Killing form allow us to define a pairing

$$\omega_{\rho_0} : H^1(\pi_1(S); \mathfrak{sl}_2\mathbb{R}) \times H^1(\pi_1(S); \mathfrak{sl}_2\mathbb{R}) \longrightarrow \mathbb{R}$$

which gives a closed non-degenerate 2-form  $\omega$  on  $X(S)$  (singular at abelian representations), i.e. a symplectic structure.

This defines a measure on  $X(S)$  by integration.

## Questions:

The hypothesis of an elliptic s.c.c. is ungainly.

**Question:** For a general closed surface with  $\chi(S) < 0$ , is almost every representation with Euler class  $\pm(\chi(S) + 1)$  a holonomy representation?

Can the “almost” be dropped?

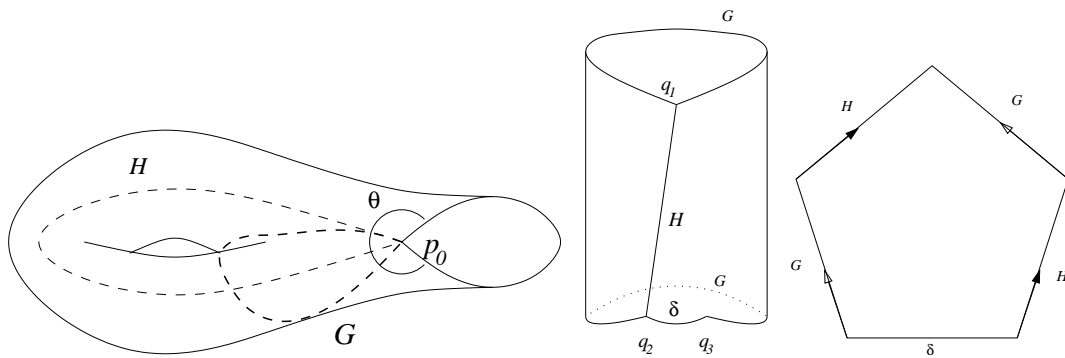
**Question:** Is *every* representation of a general closed surface,  $\chi(S) < 0$ , with Euler class  $\pm(\chi(S) + 1)$  a holonomy representation?

For two-off-extremal Euler class representations, we know not all are holonomy representations.

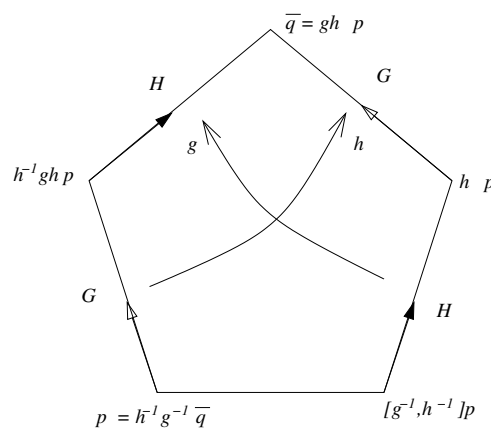
**Question:** For a given integer  $m \neq 0$ ,  $|m| \leq -\chi(S) - 1$ , and representations with  $\mathcal{E}(\rho)[S] = m$ , are holonomy representations dense/conull?

# Ideas in proof of punctured torus theorem

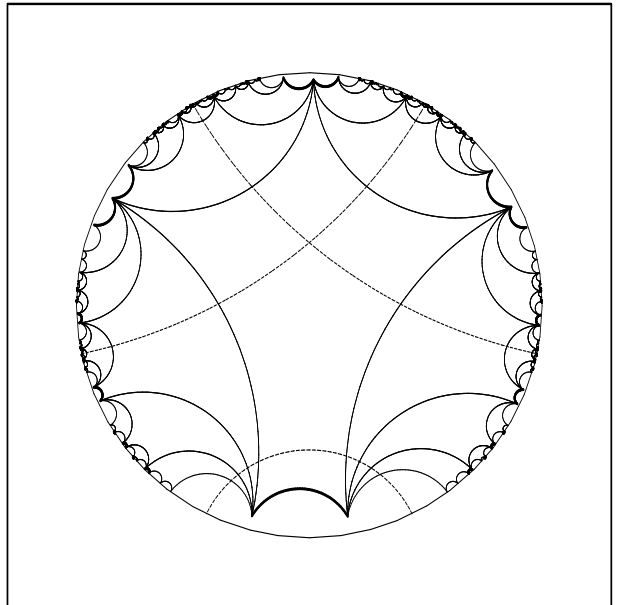
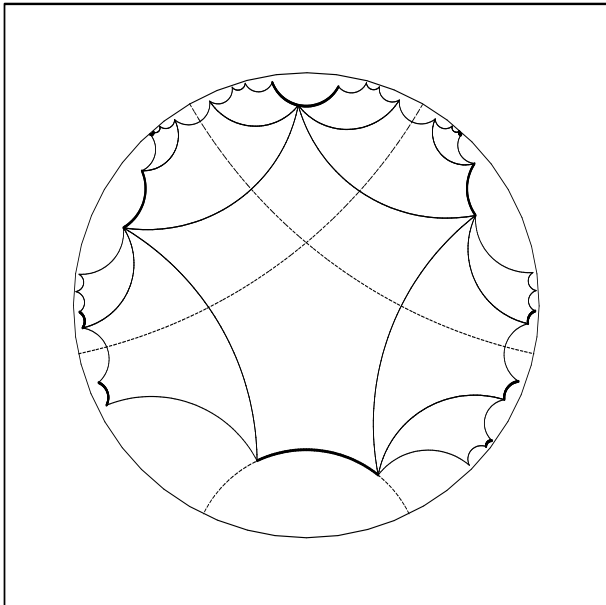
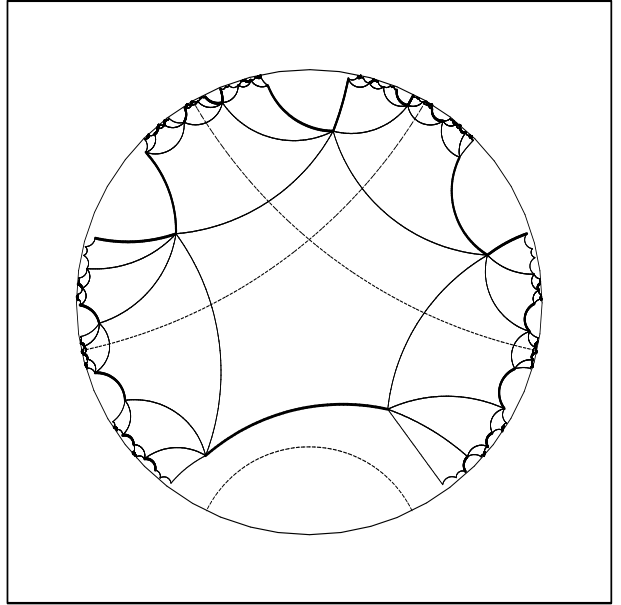
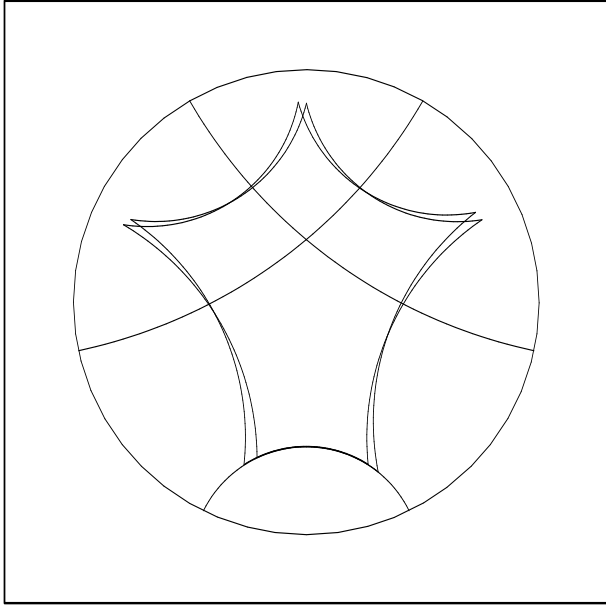
Construct a pentagonal fundamental domain.



For  $g, h \in PSL_2\mathbb{R}$  and  $p \in \mathbb{H}^2$ , we have a pentagon generated by  $g, h$  at  $p$ ,  $\mathcal{P}(g, h, p)$ .



We have a holonomy representation iff we can find a basis  $G, H$  and a point  $p \in \mathbb{H}^2$  giving a nice pentagon (non-degenerate bounding an immersed disc).



## Algebra of punctured torus representations

**Fricke, Klein 1897:** For irreducible  $\rho$ , the triple  $(\text{Tr } g, \text{Tr } h, \text{Tr } gh)$  determines  $\rho$  up to conjugacy.

Thus the character variety  $\Omega \subset \mathbb{R}^3$ .

**Nielsen 1918:** An automorphism of  $\langle G, H \rangle$  takes  $[G, H]$  to a conjugate of itself or its inverse.

If  $(\text{Tr } g, \text{Tr } h, \text{Tr } gh) = (x, y, z)$  then

$$\text{Tr}[g, h] = x^2 + y^2 + z^2 - xyz - 2 = \kappa(x, y, z).$$

Consider action of  $\text{Out } \pi_1(S) \cong GL_2\mathbb{Z}$  on  $\Omega$ , which preserves each  $\kappa^{-1}(t)$ .

Two characters are equivalent if they are related by the following moves:

$$(x, y, z) \mapsto \begin{cases} \text{permutations of coords} \\ (x, y, xy - z) \text{ ("Markoff")} \\ (-x, -y, z) \end{cases}$$



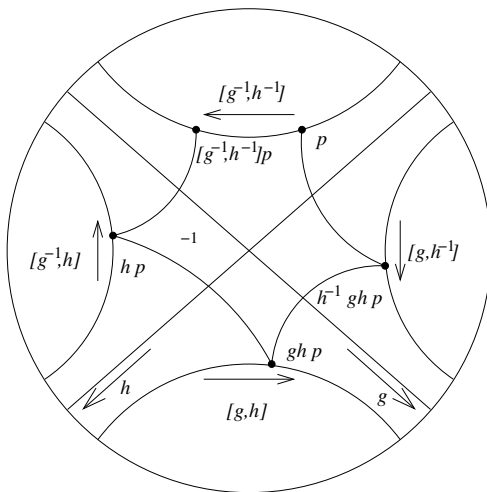
## Proof by picture.

Key lemma: for  $g, h \in PSL_2\mathbb{R}$ .

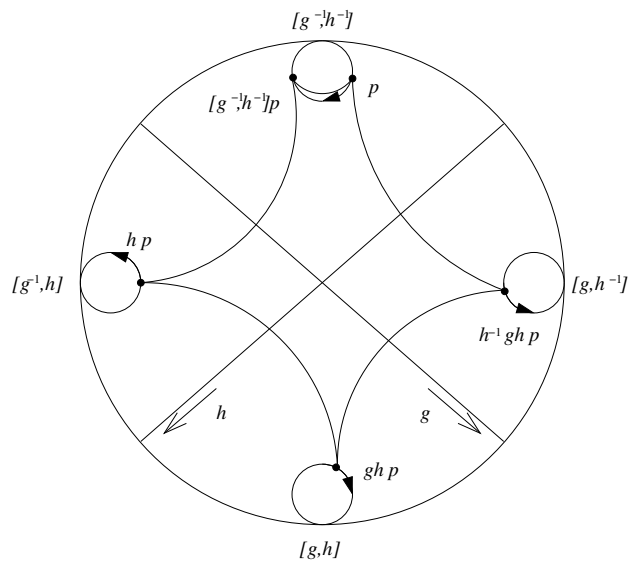
$\text{Tr}[g, h] < 2 \Leftrightarrow \{g, h \text{ hyperbolic and axes cross}\}$

Take cases according to value of  $\text{Tr}[g, h]$ .

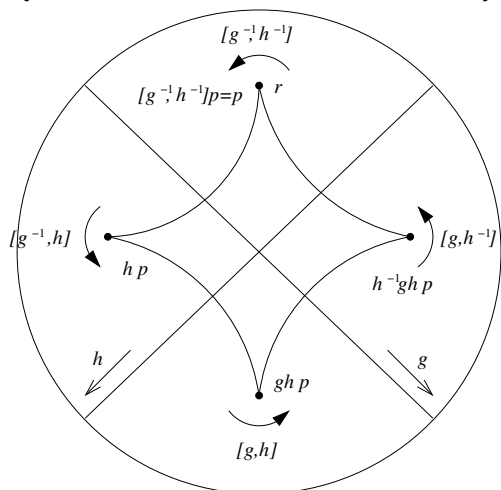
Case (i)  
 $\text{Tr}[g, h] < -2$



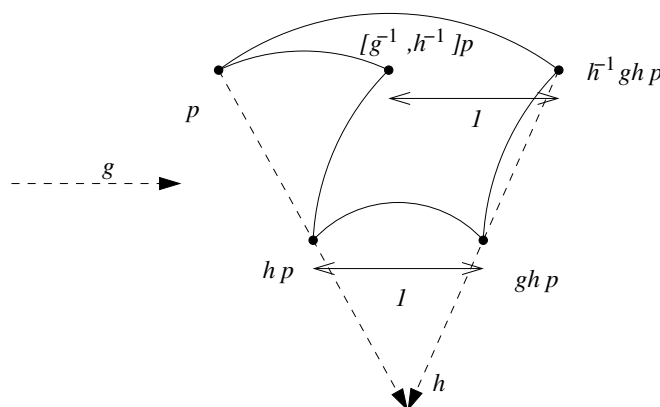
Case (ii)  
 $\text{Tr}[g, h] = -2$



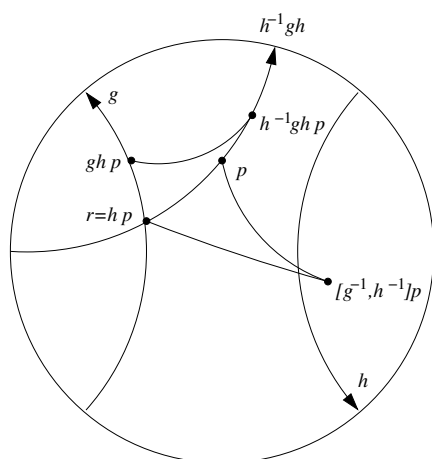
Case (iii)  
 $\text{Tr}[g, h] \in (-2, 2)$   
(Perturb carefully)



Case (iv)  
 $\text{Tr}[g, h] = 2$   
(Reducible reps)



Case (v): algorithm to change basis until character  $(x, y, z) \in (2, \infty)^3$ . Deduce arrangements of axes using results of Gilman–Maskit. Then construct.



## Ergodicity

Recall  $\text{Aut } \pi_1(S)$  acts on  $\Omega$ , describing how the character changes when we change basis of  $\pi_1(S)$ .

Goldman (1984) showed that there is a measure on  $\Omega$  (in fact, a symplectic structure on each level set  $\kappa^{-1}(t)$ ) which is invariant under the action of  $\pi_1(S)$ . In certain regions of  $\Omega$  (occurring in the present case) the action is ergodic.

Recall *ergodic* means that the only invariant sets under the action are null or conull.

Now by the mixing properties of ergodicity, by changing basis we can move from almost any such  $\rho$  to arbitrarily close to a specific  $\rho^*$ , which has the desired properties.