Overview Discrete aspects of contact geometry

Combinatorics of surfaces and dividing sets

Contact-representable automata

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Discrete Contact Geometry

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Overview	Discrete aspects	of	contact	geom

Contact-representable automata

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Outline

Overview

- Introduction
- What is contact geometry?

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- History
- Motivation
- 2 Discrete aspects of contact geometry
- Combinatorics of surfaces and dividing sets
- 4 Contact-representable automata

Contact geometry

Contact geometry is a branch of geometry that is closely related to many other fields of mathematics and mathematical physics:

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- Much classical physics: e.g. optics, thermodynamics...
- Hamiltonian mechanics / symplectic geometry

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- Much classical physics: e.g. optics, thermodynamics...
- Hamiltonian mechanics / symplectic geometry
- Complex analysis (and generalisations)
- Knot theory
- Quantum physics:

Topological quantum field theory, string theory

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- Quantum physics: Topological quantum field theory, string theory
- Parking your car.

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• Parking your car.

This talk is about some interesting recent applications that are *discrete* and *combinatorial*:

- Arrangements & combinatorics of curves on surfaces
- "Topological computation"
- Finite state automata

Contact-representable automata

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What is contact geometry?

Definition

A contact structure ξ on a 3-dimensional manifold M is a non-integrable 2-plane field on M.



Contact-representable automata

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Such ξ can be given as ker α where α is a differential 1-form satisfying $\alpha \wedge d\alpha \neq 0$ everywhere.

E.g.
$$\mathbb{R}^3$$
 with $\alpha = dz - y dx$.

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Contact-representable automata

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Flexible vs discrete

The definition of a contact structure is:

• Very *differential-geometric* (non-integrability)

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The definition of a contact structure is:

- Very *differential-geometric* (non-integrability)
- Very *flexible*: A small perturbation of a contact structure is again a contact structure. (α ∧ dα ≠ 0)

But it's also a surprisingly *rigid* type of geometry.

• Any other "nontrivial" contact structure ξ on \mathbb{R}^3 is *isotopic* to the standard one ξ_{std} .

(I.e. ξ can be continuously deformed through contact structures to ξ_{std} .)

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Criminally brief history of contact geometry

Origins:

- 18th c: Huygens' principle in optics
- 19th c: Hamiltonian mechanics

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Classical period (1900-1980):

- Hamiltonian mechanics, symplectic geometry.
- "Contact geometry = odd-dim symplectic geometry".
- Connections to much geometry and physics.

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Modern period:

 Eliashberg (1989): Distinction — *tight* (non-trivial) and overtwisted (trivial) contact structures.

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- Eliashberg (1989): Distinction *tight* (non-trivial) and overtwisted (trivial) contact structures.
- Giroux (1991): Convex surfaces and dividing sets.
- Gromov (1986), Eliashberg (1990s), ...:
 Development of *pseudoholomorphic curve* methods.
- Ozsváth-Szabó (2004), many others... : Development of *Floer homology* methods.

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Why we contactify

Some motivations for the study of contact geometry:

- *Topology:* One way to understand the topology of a manifold is to study the contact structures on it.
- Dynamics: There are natural vector fields on contact manifolds and their dynamics have important applications to classical mechanics.

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- *Dynamics:* There are natural *vector fields* on contact manifolds and their dynamics have important applications to classical mechanics.
- *Physics:* Many recent developments run parallel with physics Gromov-Witten theory, string theory, etc.
- *Pure mathematical / Structural:* Mathematical structures found in contact geometry connect to other fields...
 - Combinatorics
 - Information theory
 - Discrete mathematics

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Outline



- Discrete aspects of contact geometry
 - 4 discrete facts about contact geometry
- 3 Combinatorics of surfaces and dividing sets
- 4 Contact-representable automata

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Fact #1: Dividing sets

Consider a generic *surface S* in a contact 3-manifold *M*, possibly with boundary ∂S . (In this talk, *S* = disc or annulus.)

Fact #1 (Giroux, 1991)

A contact structure ξ near *S* is described exactly by a finite set Γ of non-intersecting smooth curves on *S*, called its *dividing set*.

Contact-representable automata

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Roughly speaking, the contact planes are

- Tangent to ∂S
- "Perpendicular" to S precisely along F

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Chord diagrams

Moreover, *isotopy* (continuous deformation) of contact structures near S corresponds to *isotopy* of dividing sets Γ .

• Interested in the *combinatorial/topological arrangement* of the curves Γ.

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Consider a disc *D* with some points *F* marked on ∂D . A *chord diagram* is a pairing of the points of *F* by

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E.g.



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Note: We can shade alternating regions of a chord diagram.

• Colour = visible side of contact plane.

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Fact #2: Overtwisted discs

Eliashberg (1989) showed that when a contact structure contains an object called an *overtwisted disc*, it is "trivial". (Reduces to study of plane fields in general.)

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Dividing sets detect trivial contact structures (OT discs).

- On a disc D, via a closed dividing curve.
- On a *sphere*, when there is *more than one* dividing curve.
Contact-representable automata

Boundary conditions

Examine what contact planes look like near boundary ∂S :



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Examine what contact planes look like near boundary ∂S :



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- Planes of ξ spin 180° between each point of F = Γ ∩ ∂S.

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E.g.: Consider contact structures ξ near a disc *D*. Fix boundary conditions *F* with |F| = 2n.

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(isotopy classes of) (tight) contact structures on $D = C_n$. Here C_n is the *n*'th *Catalan number* = $\frac{1}{n+1} {\binom{2n}{n}}$.

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E.g. *n* = 3:

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Now consider *two surfaces* intersecting transversely along a common boundary.

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Fact #3: Two surfaces intersecting

Now consider *two surfaces* intersecting transversely along a common boundary.

• Dividing sets must *interleave*.

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Fact #3: Two surfaces intersecting

Now consider *two surfaces* intersecting transversely along a common boundary.



- Dividing sets must interleave.
- We can *round the corner* in a well-defined way.

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Fact #3: Two surfaces intersecting

Now consider *two surfaces* intersecting transversely along a common boundary.



- Dividing sets must interleave.
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Fact # 3 (Honda 2000)

When surfaces intersect transversely, dividing sets interleave. Rounding corners, "turn right to dive" and "turn left to climb".

This leads to interesting combinatorics of curves...

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Fact #4: Bypasses

There's an *operation* on dividing sets called *bypass surgery*. ("Changing contact structure in the simplest possible way".)

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Fact # 4 (Honda 2000)

Bypass surgery is a natural order-3 operation on dividing sets.

Summary

Fact #1: Dividing sets (Giroux, 1991)

A contact structure ξ near *S* is described exactly by a finite set Γ of non-intersecting smooth curves on *S*, called its *dividing set*.

Fact #2: Giroux's criterion

Dividing sets detect trivial contact structures (OT discs).

- On a disc D, via a closed dividing curve.
- On a *sphere*, when there is *more than one* dividing curve.

Fact #3: Edge rounding (Honda 2000)

When surfaces intersect transversely, dividing sets interleave. Rounding edges, "turn right to dive" and "turn left to climb".

Fact #4: Bypass surgery (Honda 2000)

Bypass surgery is a natural order-3 operation on dividing sets.

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Outline



- 2 Discrete aspects of contact geometry
- Combinatorics of surfaces and dividing sets
 - Chord diagrams and cylinders
 - A vector space of chord diagrams
 - Slalom basis
 - A partial order on binary strings



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Cylinders

A combinatorial construction using dividing sets (fact #1), edge rounding (#3) and Giroux's criterion (#2):

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Insert chord diagrams into the two ends of a cylinder... ...and round corners to obtain a dividing set on S^2 .

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By Giroux's criterion, the contact structure obtained on S^2 is:

- *Trivial* (OT) if it is disconnected, i.e. contains > 1 curve.
- Nontrivial (tight) if it is connected, i.e. contains 1 curve.

Combinatorics of surfaces and dividing sets $0 \bullet 000000$

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An "inner product" on chord diagrams

Define an "inner product" function based on this construction.

Definition

 $\langle \cdot | \cdot \rangle \ : \ \{ \textit{Div sets on } D^2 \} \times \{ \textit{Div sets on } D^2 \} \longrightarrow \mathbb{Z}_2$

Combinatorics of surfaces and dividing sets $0 \bullet 000000$

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Combinatorics of surfaces and dividing sets $0 \bullet 000000$

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Proposition (M.)

For any $\Gamma, \Gamma', \Gamma''$ as above and any $\Gamma_1,$

 $\langle \Gamma | \Gamma_1 \rangle + \langle \Gamma' | \Gamma_1 \rangle + \langle \Gamma'' | \Gamma_1 \rangle = 0.$

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A vector space of chord diagrams

Idea of proof:



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A vector space of chord diagrams

Idea of proof:



These ideas lead us to define a *relation* on chord diagrams: three chord diagrams forming a bypass triple sum to 0.

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A vector space of chord diagrams

Idea of proof:



These ideas lead us to define a *relation* on chord diagrams: three chord diagrams forming a bypass triple sum to 0.

$$\bigcirc$$
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Leads to the definition of a *vector space* (over \mathbb{Z}_2).

Definition $V_n = \frac{\mathbb{Z}_2 \langle Chord \ diagrams \ with \ n \ chords \rangle}{Bypass \ relation}$

(One can show V_n is a rudimentary form of *Floer homology*...)

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A vector space of chord diagrams

Theorem (M.)

- V_n has dimension 2^{n-1} , with natural bases indexed by binary strings of length n - 1.
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A vector space of chord diagrams

Theorem (M.)

- V_n has dimension 2^{n-1} , with natural bases indexed by binary strings of length n 1.
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- The *Slalom basis* $\{S_b\}_{b \in B_{n-1}}$
- 2 The Turing tape basis $\{T_b\}_{b \in B_{n-1}}$

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The slalom basis

Construction of the *slalom* chord diagram of a binary string.



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In this basis, the bilinear form $\langle\cdot|\cdot\rangle$ has a simple description:

Theorem (M.)

$$\langle S_{a}|S_{b}
angle = \left\{egin{array}{cc} 1 & ext{if } a \preceq b \ 0 & ext{otherwise}, \end{array}
ight.$$

where \leq is a certain partial order on binary strings.

Combinatorics of surfaces and dividing sets $\circ\circ\circ\circ\circ\circ\circ\circ\circ$

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A partial order on binary strings

Definition

For two binary strings a, b, the relation $a \leq b$ holds if

a and b both contain the same number of 0s and 1s

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Inserting chord diagrams into a cylinder is a "topological machine" for comparing binary strings with respect to \leq .

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Properties of \leq

Recall we said the slalom chord diagrams form a basis for V_n .

E.g.



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Combinatorics of surfaces and dividing sets $\circ \circ \circ \circ \circ \circ \circ \circ \circ$

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Combinatorics of surfaces and dividing sets $\circ \circ \circ \circ \circ \circ \circ \circ \circ$

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 $= S_{0011} + S_{0110} + S_{1001} + S_{1010}$

- We say the *component strings* of Γ are 0011, 0110, 1001, 1010.
- Given a chord diagram Γ , let $b_{-}(\Gamma)$ denote the numerically least, and $b_{+}(\Gamma)$ the numerically greatest, component string.

So for the example Γ above, $b_{-}(\Gamma) = 0011$ and $b_{+}(\Gamma) = 1010$.

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Partial order \leq and Catalan numbers

The partial order \leq has interesting combinatorics...

Combinatorics of surfaces and dividing sets $\circ\circ\circ\circ\circ\circ\circ\bullet$

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Partial order \leq and Catalan numbers

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Theorem (M.)

• For any chord diagram Γ , $b_{-}(\Gamma) \leq b_{+}(\Gamma)$.

Combinatorics of surfaces and dividing sets $\circ\circ\circ\circ\circ\circ\circ\bullet$

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Theorem (M.)

- For any chord diagram Γ , $b_{-}(\Gamma) \leq b_{+}(\Gamma)$.
- Por any pair of strings s₋, s₊ satisfying s₋ ≤ s₊, there exists a unique chord diagram Γ such that b₋(Γ) = s₋ and b₊(Γ) = s₊.

Combinatorics of surfaces and dividing sets $\circ\circ\circ\circ\circ\circ\circ\bullet$

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... and produces the Catalan numbers again.

Corollary

The number of pairs of strings s_-, s_+ of length n such that $s_- \leq s_+$ is C_{n+1} .

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Outline



- Discrete aspects of contact geometry
- Combinatorics of surfaces and dividing sets
- 4 Contact-representable automata
 - Turing tape basis
 - Cubulated inner product
 - Finite state automata

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The Turing tape basis

Divide the disc with |F| = 2n into n - 1 squares:



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On each square there are two "basic" possible sets of sutures

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Draw them according to a string *b* to obtain Turing tape basis diagrams T_b — another basis for V_n . E.g.

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Cubulated inner product

With chord diagrams are drawn in "Turing tape" form, the inner product $\langle\cdot|\cdot\rangle$ becomes "cubulated"...

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Contact-representable automata

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With chord diagrams are drawn in "Turing tape" form, the inner product $\langle \cdot | \cdot \rangle$ becomes "cubulated"...

E.g.
$$\langle T_{1011} | T_{1000} \rangle =$$





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Cubulation, step by step

Draw curves curvier, and analyse this computation in step-by-step fashion.



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Overview Discrete aspects of contact geometry

Combinatorics of surfaces and dividing sets

Contact-representable automata

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A finite state automaton

We can consider this process as a *finite state automaton*.



Contact-representable automata

A finite state automaton

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We can consider this process as a *finite state automaton*.

(or anything with a closed curve)

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A finite state automaton

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Definition

A finite state automaton is contact-representable if:

- To every state s ∈ S is associated a dividing set Γ_s on a disc with 2n fixed boundary points.
- To each input σ ∈ Σ is associated a dividing set Γ_σ on an annulus with 2n fixed points on each boundary circle.

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E.g. for the previous example n = 2, 3 states: $\Gamma_A = \bigcap \Gamma_B = \bigcap \Gamma_{\perp}$: (or anything with a closed curve)

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Quantum information theory and computation

Question

Which finite state automata can be represented by contact geometry in this way?

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Quantum information theory and computation

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Various applications:

• These constructions give linear maps $V_n \longrightarrow V_n$ which form a Topological quantum field theory.

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Quantum information theory and computation

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- These constructions give linear maps $V_n \longrightarrow V_n$ which form a Topological quantum field theory.
- The above is a toy model of a quantum theory which explicitly encodes information: "it from bit".

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- Moreover, this is a TQFT which explicitly encodes computation.
- Quantum states based on curves on surfaces and topology are considered in the physical theory of "anyons".
- A very combinatorial, geometric way of performing certain computations.
- A reversible / conservative type of computation.

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Thanks for listening!

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