Background

Trinities and sutured manifolds

Invariants of sutured manifold trinities

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Trinities, sutured Floer homology, and contact structures

Daniel V. Mathews ¹ joint with Tamás Kálmán ²

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> Kioloa, ANU 12 January 2016

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Overview

This talk is about

- trinities a type of triality arising in graph theory
- sutured Floer homology an extension of Heegaard Floer homology to 3-manifolds with (sutured) boundary
- contact structures on 3-manifolds.

In progress / joint with T. Kálmán. Building on work of Friedl, Juhasz, Kálmán, Rasmussen, Etnyre, Honda, Kazez, Ozsváth, Szabó, Witten, Floer ...

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Overview

This talk will:

- Briefly introduce background ideas
 - sutured 3-manifolds
 - Heegaard Floer homology, sutured Floer homology
 - contact structures & classifying them
 - trinities in graph theory

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 - trinities in graph theory
- Introduce certain triples of sutured 3-manifolds associated to trinities

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 - sutured 3-manifolds
 - Heegaard Floer homology, sutured Floer homology
 - contact structures & classifying them
 - trinities in graph theory
- Introduce certain triples of sutured 3-manifolds associated to trinities
- Discuss how they are in triality
 - isomorphic sutured Floer homology
 - bijections between contact structures
 - isomorphisms of related polytopes

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Background

- Sutured 3-manifolds
- Floer homology
- Contact structures
- Trinities



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Sutured 3-manifolds

A sutured 3-manifold (M, Γ) is a 3-manifold M with some decorations Γ on its boundary.

• Decorations consist of oriented curves (sutures) on ∂M .

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- Decorations consist of oriented curves (sutures) on ∂M .
- Γ splits ∂M into "positive" and "negative" regions R_±, oriented in a coherent way.

•
$$\partial R_+ = -\partial R_- = \Gamma$$

• when you cross Γ , you go from R_+ to R_- .

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A sutured 3-manifold is balanced if $\chi(R_+) = \chi(R_-)$. We're interested in some specific sutured 3-manifolds...

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Heegaard Floer homology

Heegaard Floer homology gives invariants of closed 3-manifolds.

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Heegaard Floer homology

Heegaard Floer homology gives invariants of closed 3-manifolds.

Given a closed 3-manifold *M*, essentially:

- Heegaard Floer homology of *M* is Lagrangian intersection Floer homology of a manifold constructed from a Heegaard decomposition (Σ, α, β) of *M*.
 - Σ a closed surface of genus g
 - $\alpha = \{\alpha_1, \dots, \alpha_g\}, \beta = \{\beta_1, \dots, \beta_g\}$ Heegaard curves.

Much of this extends to the case of a sutured 3-manifold.

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Heegaard Floer homology

More specifically:

• If Σ has genus g, take Sym^g Σ



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Heegaard Floer homology

- If Σ has genus g, take Sym^g Σ
- Lagrangian submanifolds given by $\mathbb{T}_{\alpha} = \alpha_1 \times \cdots \times \alpha_g$ and $\mathbb{T}_{\beta} = \beta_1 \times \cdots \times \beta_g$

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- Form a chain complex generated by intersection points $\mathbb{T}_{\alpha} \cap \mathbb{T}_{\beta}$

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Heegaard Floer homology

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- Form a chain complex generated by intersection points $\mathbb{T}_{\alpha} \cap \mathbb{T}_{\beta}$
- For $\mathbf{x}, \mathbf{y} \in \mathbb{T}_{\alpha} \cap \mathbb{T}_{\beta}$, consider holomorphic curves "from" \mathbf{x} "to" \mathbf{y} in Sym^g Σ

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Heegaard Floer homology

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- Such curves which are suitably rigid give a boundary operator ∂ and ∂² = 0.

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- Such curves which are suitably rigid give a boundary operator ∂ and ∂² = 0.
- $\widehat{HF}(M)$ is the homology of this complex and is an invariant of *M* (independent of all other choices).

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Heegaard Floer homology

More specifically:

- If Σ has genus g, take Sym^g Σ
- Lagrangian submanifolds given by $\mathbb{T}_{\alpha} = \alpha_1 \times \cdots \times \alpha_g$ and $\mathbb{T}_{\beta} = \beta_1 \times \cdots \times \beta_g$
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- For $\mathbf{x}, \mathbf{y} \in \mathbb{T}_{\alpha} \cap \mathbb{T}_{\beta}$, consider holomorphic curves "from" \mathbf{x} "to" \mathbf{y} in Sym^g Σ
- Such curves which are suitably rigid give a boundary operator ∂ and ∂² = 0.
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Powerful invariant, categorifies Alexander polynomial, computes genus of knots, etc...

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Sutured Floer homology

Idea of sutured Floer homology (Juhász): extend \widehat{HF} to sutured 3-manifolds.

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Sutured manifolds also have Heegaard decompositions (Σ, α, β) :

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- Compact orientable surface Σ , genus g, with boundary
- Take $\Sigma \times [0, 1]$, glue discs to $\alpha \times \{0\}$, $\beta \times \{1\}$

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- Take $\Sigma \times [0, 1]$, glue discs to $\alpha \times \{0\}$, $\beta \times \{1\}$
- Boundary then consists of
 - $\partial \Sigma \times [0,1] = \Gamma$
 - $\Sigma \times \{0\}$ (surgered along α) = R_{-}
 - $\Sigma \times \{1\}$ (surgered along β) = R_+

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If manifold is balanced, then $\#\alpha = \#\beta$ and one can define $SFH(M, \Gamma)$ in a completely analogous way to \widehat{HF} .

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If manifold is balanced, then $\#\alpha = \#\beta$ and one can define $SFH(M, \Gamma)$ in a completely analogous way to \widehat{HF} . Generalises \widehat{HF} in several cases:

- closed manifold
- knot Floer homology
- knots with Seifert surfaces

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Contact structures

A contact structure on a 3-manifold *M* is a non-integrable 2-plane field $\xi = \ker \alpha$.



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Contact topology question: Given a 3-manifold M, how many (isotopy classes of) contact structures are there on M?

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Contact topology question: Given a 3-manifold M, how many (isotopy classes of) contact structures are there on M? Two types of contact structures: tight and overtwisted.

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Contact topology question: Given a 3-manifold M, how many (isotopy classes of) contact structures are there on M? Two types of contact structures: tight and overtwisted.

An overtwisted contact structure is one containing an overtwisted disc:



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Contact 3-manifolds

Overtwisted contact structures are equivalent to homotopy classes of 2-plane fields (Eliashberg 1989).

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Contact 3-manifolds

Overtwisted contact structures are equivalent to homotopy classes of 2-plane fields (Eliashberg 1989).

• Question: How many isotopy classes of tight contact structures are there on *M*?

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Contact 3-manifolds

Overtwisted contact structures are equivalent to homotopy classes of 2-plane fields (Eliashberg 1989).

• Question: How many isotopy classes of tight contact structures are there on *M*?

For a closed oriented atoroidal 3-manifold *M*, there are finitely many isotopy classes of tight contact structures (Colin–Giroux–Honda 2002).

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Contact 3-manifolds

Overtwisted contact structures are equivalent to homotopy classes of 2-plane fields (Eliashberg 1989).

• Question: How many isotopy classes of tight contact structures are there on *M*?

For a closed oriented atoroidal 3-manifold *M*, there are finitely many isotopy classes of tight contact structures (Colin–Giroux–Honda 2002). For 3-manifolds with boundary:

- natural boundary conditions for contact structures are given by sutures.
- Roughly, sutures Γ on ∂M prescribe a contact structure up to isotopy near ∂M.
- This is via Giroux's theory of convex surfaces (1991).

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Convex surfaces and sutures

A generic surface *S* in a contact 3-manifold is convex: \exists a contact vector field *X* transverse to *S*.

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Convex surfaces and sutures

A generic surface *S* in a contact 3-manifold is convex: \exists a contact vector field *X* transverse to *S*. The dividing set Γ and R_{\pm} are given by

$$\begin{split} \mathsf{\Gamma} &= \{ p \in S \ : \ X_p \in \xi_p \} = \{ p \in S \ : \ \alpha_p(X_p) = 0 \} \\ \mathsf{R}_{\pm} &= \{ p \in S \ : \ \alpha_p(X_p) \gtrless 0 \} \end{split}$$



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(Roughly: think of *S* as "horizontal", *X* as "vertical", Γ is "where ξ is vertical".)


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(Roughly: think of *S* as "horizontal", *X* as "vertical", Γ is "where ξ is vertical".)

If $\partial S \neq \emptyset$, require ∂S to be Legendrian (tangent to ξ).



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Contact corners

When two convex surfaces meet along a boundary, contact planes are arranged as shown.



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Honda (2000): contact structures can be built up using a small contact 3-manifold called a *bypass* (=half an overtwisted disc).



"All topologically trivial contact topology is constructed from bypasses."

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Bypasses



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Contact invariants in Heegaard Floer homology

Heegaard Floer homology gives invariants of contact structures:

- ξ on closed $M \rightsquigarrow c(\xi) \in \widehat{HF}(-M)$.
- ξ on sutured $(M, \Gamma) \rightsquigarrow c(\xi) \in SFH(-M, -\Gamma)$.

(Ozsváth–Szazó, Honda–Kazez–Matić) Can be defined via open book decompositions...

Background

Trinities and sutured manifolds

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Trinities

 Consider a bipartite planar graph G, with vertex classes V (violet/blue), E (emerald/green).



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- Consider a bipartite planar graph G, with vertex classes V (violet/blue), E (emerald/green).
- Add vertices *R* (red) in complementary regions.



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- Alternating colouring on triangles.



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- Subdivision → triangulation of S² with all triangles containing one vertex of each colour.
- Colour edges by complementary colour to endpoints.
- Alternating colouring on triangles.



(Alternately can start from triangulation and colour in.)

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These three planar graphs form a trinity and have many interesting properties.



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These three planar graphs form a trinity and have many interesting properties.



- Dual graphs are naturally oriented.
- Tutte's tree trinity theorem: G^{*}_V, G^{*}_E, G^{*}_R have same number ρ of spanning arborescences.
- Define this number as the arborescence number or magic number of the trinity.

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Hypertrees

• A hypergraph is a pair $\mathcal{H} = (V, E)$ where V is a set of vertices and E is a (multi-)set of hyperedges.



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Graph = hypergraph with each hyperedge containing 2 vertices.

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• \mathcal{H} naturally determines a bipartite graph Bip \mathcal{H} with vertex classes V, E: join v to e iff $v \in e$. Introduction Background Trinities and sutured manifolds

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Hypertrees

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- Conversely, any bipartite graph is a hypergraph in two dual ways (V, E), (E, V) — abstract dual.

A hypertree in $\mathcal{H} = (V, E)$ is a function $f : E \to \mathbb{N}_0$ such that \exists a spanning tree in Bip \mathcal{H} with degree f(e) + 1 at each $e \in E$.

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Hypertrees

 The set of hypertrees of hypergraph (V, E) is a subset of Z^E.

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Hypertr	ees		

- The set of hypertrees of hypergraph (V, E) is a subset of \mathbb{Z}^{E} .
- In fact, the set of hypertrees of a hypergraph is a convex lattice polytope Q_(V,E) (Postnikov 2009, Kálmán 2013).

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Hypertre	ees		

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In a trinity (V, E, R), there are naturally six hypergraphs:

(V, E), (E, V), (E, R), (R, E), (R, V), (V, R).

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How many hypertrees do they have?
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- The set of hypertrees of hypergraph (V, E) is a subset of \mathbb{Z}^E .
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In a trinity (V, E, R), there are naturally six hypergraphs:

(V, E), (E, V), (E, R), (R, E), (R, V), (V, R).

How many hypertrees do they have?

Hypertrees

Theorem (Postnikov 2009, Kálmán 2013)

The number of hypertrees in any of these hypergraphs is equal to the magic number of the trinity:

$$\rho = |Q_{(V,E)}| = |Q_{(E,V)}| = |Q_{(E,R)}| = |Q_{(R,E)}| = |Q_{(R,V)}| = |Q_{(V,R)}|$$

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 - $\bullet~$ Bipartite planar graphs \rightarrow sutured manifolds
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From bipartite planar graphs to sutured manifolds

Given a planar graph *G*, there is a natural way to construct a surface F_G bounding an alternating link L_G : the median construction.

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From bipartite planar graphs to sutured manifolds

Given a planar graph *G*, there is a natural way to construct a surface F_G bounding an alternating link L_G : the median construction.

- Take a regular neighbourhood of G in the plane (ribbon).
- Insert a negative half twist over each edge of *G* to obtain F_G . Then $L_G = \partial F_G$.



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From bipartite planar graphs to sutured manifolds

When G is bipartite, F_G is oriented: a Seifert surface for L_G .

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From bipartite planar graphs to sutured manifolds

When G is bipartite, F_G is oriented: a Seifert surface for L_G .

• In this case L_G is *special alternating* and F_G is a minimal genus Seifert surface (Murasugi 1958, Crowell 1959, Gabai 1986).

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From bipartite planar graphs to sutured manifolds

When *G* is bipartite, F_G is oriented: a Seifert surface for L_G .

- In this case L_G is special alternating and F_G is a minimal genus Seifert surface (Murasugi 1958, Crowell 1959, Gabai 1986).
- In fact, any minimal genus Seifert surface of a non-split prime special alternating link arises as such an F_G (Hirasawa–Sakuma 1996, Banks 2011).

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Trinity of sutured manifolds

From a trinity of bipartite graphs, we obtain a trinity of alternating links with Seifert surfaces



and sutured 3-manifolds

$$(S^3 - F_{G_V}, L_{G_V}), (S^3 - F_{G_E}, L_{G_E}), (S^3 - F_{G_R}, L_{G_R}).$$

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Trinity of sutured manifolds

Question: For each of $(S^3 - F_{G_V}, L_{G_V})$, $(S^3 - F_{G_E}, L_{G_E})$, $(S^3 - F_{G_R}, L_{G_R})$:

- What is SFH?
- e How many (isotopy classes of) tight contact structures
- **(a)** What are contact invariants $c(\xi) \in SFH$?

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- Invariants of sutured manifold trinities
 - SFH
 - Contact structures on sutured manifold trinities
 - Contact invariants of sutured manifold trinities

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SFH of sutured manifold trinities

Answer to Q1 is known, thanks to a result of Juhász–Kálmán–Rasmussen (2012):

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SFH of sutured manifold trinities

Answer to Q1 is known, thanks to a result of Juhász–Kálmán–Rasmussen (2012):

• Essentially, $SFH(S^3 - F_G, L_G)$ "is" the lattice polytope of hypertrees on the associated hypergraph.

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To understand this properly, we need some further background on gradings on *SFH*.

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To understand this properly, we need some further background on gradings on *SFH*.

- homological grading
- spin-c grading

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Spin-c structures and SFH

• Recall a spin-c structure on a closed 3-manifold *M* is a homology class of nonvanishing vector field.

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Spin-c structures and SFH

- Recall a spin-c structure on a closed 3-manifold *M* is a homology class of nonvanishing vector field.
- Two vector fields are homologous if they are homotopic in the complement of a 3-ball in *M*.

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A spin-c structure on a sutured 3-manifold (M, Γ) ?

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- Recall a spin-c structure on a closed 3-manifold *M* is a homology class of nonvanishing vector field.
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- A spin-c structure on a sutured 3-manifold (M, Γ) ?
 - a homology class of nonvanishing vector field *v* which has a specified form along ∂*M*:

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 - a homology class of nonvanishing vector field v which has a specified form along ∂M:
 - v must point into M along R_- , out of M along R_+
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In both cases, the space of spin-c structures is affine over $H_1(M)$:

 $\operatorname{Spin}^{c}(M,\Gamma) \cong H_{1}(M;\mathbb{Z}).$

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Spin-c structures and SFH

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SFH decomposes over spin-c structures:

$$SFH(M,\Gamma) \cong \bigoplus_{\mathfrak{s}\in \operatorname{Spin}^{c}(M,\Gamma)} SFH(M,\Gamma,\mathfrak{s}).$$

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Spin-c decomposition of SFH of a trinity

Each $(S^3 - F_G, L_G)$ is an example of a sutured *L*-space (Friedl–Juhász–Rasmussen 2011).

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Spin-c decomposition of SFH of a trinity

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A sutured *L*-space is a balanced sutured 3-manifold (*M*, Γ) such that SFH(*M*, Γ) is torsion free and supported in a single Z/2 homological grading.

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- Friedl–Juhász–Rasmussen proved that if (M, Γ) is a sutured L-space and s is a spin-c structure, then SFH(M, Γ, s) is either trivial or Z.

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- Friedl–Juhász–Rasmussen proved that if (M, Γ) is a sutured L-space and s is a spin-c structure, then SFH(M, Γ, s) is either trivial or Z.

Thus to know *SFH* of a sutured *L*-space it is sufficient to know the support

 $S(M,\Gamma) = \{ \mathfrak{s} \in \operatorname{Spin}^{c}(M,\Gamma) : SFH(M,\Gamma,\mathfrak{s}) \neq 0 \}.$

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Spin-c decomposition of SFH of a trinity

Taking $G = G_R$ planar bipartite with vertex classes (V, E),

$$S^3 - F_{G_R} \cong S^3 - G$$
, handlebody of genus $|R| - 1$.



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Spin-c decomposition of SFH of a trinity

Taking $G = G_R$ planar bipartite with vertex classes (V, E),

 $S^3 - F_{G_R} \cong S^3 - G$, handlebody of genus |R| - 1.



$${
m Spin}^c(S^3-F_{G_R},L_{G_R})\ \cong H_1(S^3-G_R)\cong \mathbb{Z}^{|R|-1}$$

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Spin-c decomposition of SFH of a trinity

Taking $G = G_R$ planar bipartite with vertex classes (V, E),

 $S^3 - F_{G_R} \cong S^3 - G$, handlebody of genus |R| - 1.



$$\begin{aligned} & \operatorname{Spin}^{c}(S^{3} - F_{G_{R}}, L_{G_{R}}) \\ & \cong H_{1}(S^{3} - G_{R}) \cong \mathbb{Z}^{|R|-1}. \end{aligned}$$

$$& \operatorname{So} SFH(S^{3} - F_{G_{R}}, L_{G_{R}}) \text{ has s}$$

So $SFH(S^3 - F_{G_R}, L_{G_R})$ has support in $\mathbb{Z}^{|R|-1}$.

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Spin-c decomposition of SFH of a trinity

Taking $G = G_R$ planar bipartite with vertex classes (V, E),

 $S^3 - F_{G_R} \cong S^3 - G$, handlebody of genus |R| - 1.



$$\begin{array}{l} \text{Spin}^{c}(S^{3}-F_{G_{R}},L_{G_{R}})\\ \cong H_{1}(S^{3}-G_{R})\cong \mathbb{Z}^{|R|-1}.\\ \text{So }SFH(S^{3}-F_{G_{R}},L_{G_{R}}) \text{ has support in } \mathbb{Z}^{|R|-1}. \end{array}$$

On the other hand, consider hypergraph (E, R):

- Vertices = E
- Hyperedges = R.

Hypertrees form a polytope in \mathbb{Z}^{R} .



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Spin-c decomposition of SFH of a trinity

Taking $G = G_R$ planar bipartite with vertex classes (V, E),

 $S^3 - F_{G_R} \cong S^3 - G$, handlebody of genus |R| - 1.



$$\begin{split} & \text{Spin}^{c}(S^{3}-F_{G_{R}},L_{G_{R}}) \\ & \cong H_{1}(S^{3}-G_{R}) \cong \mathbb{Z}^{|R|-1}. \\ & \text{So } SFH(S^{3}-F_{G_{R}},L_{G_{R}}) \text{ has support in } \mathbb{Z}^{|R|-1}. \end{split}$$

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SFH of a trinity

So SFH support $S(S^3 - F_{G_R}, L_{G_R}) \subset \mathbb{Z}^{|R|-1}$, and hypertree polytope $Q_{(E,R)} \subset \mathbb{Z}^R$.



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SFH of a trinity

So SFH support $S(S^3 - F_{G_R}, L_{G_R}) \subset \mathbb{Z}^{|R|-1}$, and hypertree polytope $Q_{(E,R)} \subset \mathbb{Z}^R$.

Theorem (Juhász–Kálmán–Rasmussen)

There is an natural embedding $\text{Spin}^{c}(M, \Gamma) = \mathbb{Z}^{|R|-1} \subset \mathbb{Z}^{|R|}$ so that

$$S(S^3 - F_{G_R}, L_{G_R}) \cong Q_{(E,R)}$$

I.e. support of SFH "is" hypertree polytope.

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dim
$$SFH(S^3 - F_{G_R}, L_{G_R}) = |Q_{(E,R)}| = \rho$$
 magic number.
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dim
$$SFH(S^3 - F_{G_R}, L_{G_R}) = |Q_{(E,R)}| = \rho$$
 magic number.
Similarly, $S(S^3 - F_{G_R}, L_{G_R}) \cong -Q_{(V,R)}$.

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SFH of a trinity

It follows that

$$SFH(S^3 - F_{G_V}, L_{G_V}), \quad SFH(S^3 - F_{G_E}, L_{G_E}), \quad SFH(S^3 - F_{G_R}, L_{G_R})$$

all have dimension given by magic number, corresponding to

$$|Q_{(V,E)}| = |Q_{(E,V)}| = |Q_{(E,R)}| = |Q_{(R,E)}| = |Q_{(R,V)}| = |Q_{(V,R)}| = \rho.$$



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Duality of polytopes

Postnikov related dual polytopes $Q_{(V,E)} \subset \mathbb{Z}^{E}$, $Q_{(E,V)} \subset \mathbb{Z}^{V}$.

$$Q_{(V,E)} = \left(\sum_{v \in V} \Delta_v\right) - \Delta_E = Q^+_{(V,E)} - \Delta_E,$$

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where $\Delta_v = \text{Conv}\{e : v \in e\}, \Delta_E = \text{Conv}\{e : e \in E\}$, and subtraction is Minkowski difference.

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Duality of polytopes

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where $\Delta_{v} = \text{Conv}\{e : v \in e\}, \Delta_{E} = \text{Conv}\{e : e \in E\}$, and subtraction is Minkowski difference. The "untrimmed polytopes" $Q^{+}_{(V,E)}, Q^{+}_{(E,V)}$ are related via a higher-dimensional root polytope in $\mathbb{R}^{V} \oplus \mathbb{R}^{E}$

$$Q = \operatorname{Conv} \{ e + v : v \in e \} \subset \mathbb{R}^{V} \oplus \mathbb{R}^{E}.$$

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Duality of polytopes

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$$Q_{(V,E)} = \left(\sum_{v \in V} \Delta_v\right) - \Delta_E = Q^+_{(V,E)} - \Delta_E,$$

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$$Q = \operatorname{Conv} \{ e + v : v \in e \} \subset \mathbb{R}^{V} \oplus \mathbb{R}^{E}.$$

Essentially they are projections of Q, e.g.: $\pi_V : \mathbb{R}^V \oplus \mathbb{R}^E \to \mathbb{R}^V$

$$Q^+_{(V,E)} \cong |V| \left(Q \cap \pi_V^{-1} \left(\frac{1}{|V|} \sum_{v \in V} v \right) \right)$$

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Duality of polytopes

$$\begin{aligned} \mathcal{Q}_{(V,E)} &= \left(\sum_{v \in V} \Delta_v\right) - \Delta_E = \mathcal{Q}^+_{(V,E)} - \Delta_E, \\ \mathcal{Q} &= \operatorname{Conv} \left\{ \boldsymbol{e} + \boldsymbol{v} \ : \ \boldsymbol{v} \in \boldsymbol{e} \right\} \subset \mathbb{R}^V \oplus \mathbb{R}^E. \\ \mathcal{Q}^+_{(V,E)} &\cong |V| \ \left(\mathcal{Q} \cap \pi_V^{-1} \left(\frac{1}{|V|} \sum_{v \in V} \boldsymbol{v} \right) \right) \end{aligned}$$

Question

Does this root polytope have a symplectic or Floer-theoretic interpretation?

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SFH of a trinity

Theorem (Juhász–Kálmán–Rasmussen)

$$S(S^3 - F_{G_R}, L_{G_R}) \cong Q_{(E,R)}$$

Ideas of proof:



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SFH of a trinity

Theorem (Juhász–Kálmán–Rasmussen)

$$S(S^3 - F_{G_R}, L_{G_R}) \cong Q_{(E,R)}$$

Ideas of proof:

- Friedl–Juhász–Ramsussen (2011) proved that the Euler characteristic χ(SFH(M, Γ, s)) is given by the Turaev torsion of the pair (M, R_).
- This torsion can be calculated by using Fox calculus and the map $\pi_1(R_-) \rightarrow \pi_1(M)$.

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- This torsion can be calculated by using Fox calculus and the map $\pi_1(R_-) \rightarrow \pi_1(M)$.
- The Fox calculus yielding Turaev torsion of (S³ F_{G_R}, L_{G_R}) is equal to the determinant of a certain adjacency matrix for the trinity.
- Terms in this determinant are monomials corresponding to lattice points in the polytope Q_(E,R).

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Contact structures on trinities

Q2: How many isotopy classes of tihgt contact structures on sutured manifolds of a trinity?

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Contact structures on trinities

Q2: How many isotopy classes of tihgt contact structures on sutured manifolds of a trinity?

Theorem (Kálmán–M.)

The number of isotopy classes of tight contact structures on $(S^3 - F_{G_R}, L_{G_R})$ is given by

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Contact structures on trinities

Q2: How many isotopy classes of tihgt contact structures on sutured manifolds of a trinity?

Theorem (Kálmán–M.)

The number of isotopy classes of tight contact structures on $(S^3 - F_{G_R}, L_{G_R})$ is given by ρ , the magic number of the trinity.

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Contact structures on trinities

Q2: How many isotopy classes of tihgt contact structures on sutured manifolds of a trinity?

Theorem (Kálmán–M.)

The number of isotopy classes of tight contact structures on $(S^3 - F_{G_R}, L_{G_R})$ is given by ρ , the magic number of the trinity. Moreover, there is precisely one isotopy class of tight contact structure in each Spin^c class in the support $S(S^3 - F_G, L_G)$ of SFH.

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The number of isotopy classes of tight contact structures on $(S^3 - F_{G_R}, L_{G_R})$ is given by ρ , the magic number of the trinity. Moreover, there is precisely one isotopy class of tight contact structure in each Spin^{*c*} class in the support $S(S^3 - F_G, L_G)$ of SFH.

Proof gives explicit bijections

{contact structures} \cong {hypertrees on (*E*, *R*)} \cong {Spin^{*c*} structures},

and is constructive.

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Contact structures on trinities

Theorem (Kálmán–M.)

The number of isotopy classes of tight contact structures on $(S^3 - F_G, L_G)$ is given by ρ , the magic number of the trinity.

Proof ideas:

• $S^3 - F_G$ can be cut into two 3-balls by |R| convex discs D_i in the complementary regions of *G*

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Contact structures on trinities

Theorem (Kálmán–M.)

The number of isotopy classes of tight contact structures on $(S^3 - F_G, L_G)$ is given by ρ , the magic number of the trinity.

- $S^3 F_G$ can be cut into two 3-balls by |R| convex discs D_i in the complementary regions of G
- **2** A choice of dividing set Γ_i on each D_i determines at most one tight contact structure on $(S^3 F_G, L_G)$.

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- **2** A choice of dividing set Γ_i on each D_i determines at most one tight contact structure on $(S^3 F_G, L_G)$.
- A spanning tree *T* representing a hypertree yields a dividing set on each *D_i* by taking the boundary of a ribbon.

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- Analyse bypasses in between the two 3-balls, use Honda's gluing theorem to prove contact structures are tight.

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- **2** A choice of dividing set Γ_i on each D_i determines at most one tight contact structure on $(S^3 F_G, L_G)$.
- A spanning tree T representing a hypertree yields a dividing set on each D_i by taking the boundary of a ribbon.
- Analyse bypasses in between the two 3-balls, use Honda's gluing theorem to prove contact structures are tight.
- Use Kálmán's work: there are ρ hypertrees; two spanning trees representing same hypertree produce contact structures related by bypasses.

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Consider complements of tubular neighbourhood of G:



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Consider complements of tubular neighbourhood of G:



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Consider complements of tubular neighbourhood of G:



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Now just take one side of the plane:



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Now just take one side of the plane:



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A spanning tree in (E, R)



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A spanning tree in (E, R) yields a dividing set



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Contact invariants of sutured manifold trinities

Q3: What about contact invariants of these contact structures?

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Contact invariants of sutured manifold trinities

Q3: What about contact invariants of these contact structures? From Q2, there is one (isotopy class of) tight contact structure $\xi_{\mathfrak{s}}$ for each spin-c structure \mathfrak{s} , so

$$c(\xi_{\mathfrak{s}})\in SFH(S^3-F_G,L_G,\mathfrak{s})\cong\mathbb{Z}.$$

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Contact invariants of sutured manifold trinities

Q3: What about contact invariants of these contact structures? From Q2, there is one (isotopy class of) tight contact structure ξ_{s} for each spin-c structure s, so

$${\boldsymbol{c}}(\xi_{\mathfrak{s}})\in {\boldsymbol{SFH}}({\boldsymbol{S}}^3-{\boldsymbol{F}}_{{\boldsymbol{G}}},{\boldsymbol{L}}_{{\boldsymbol{G}}},\mathfrak{s})\cong \mathbb{Z}.$$

Theorem (Kálmán–M.)

 $c(\xi_{\mathfrak{s}})$ generates $SFH(S^3 - F_G, L_G, \mathfrak{s})$.

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Theorem (Kálmán–M.)

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c(\xi_{\mathfrak{s}}) generates SFH(S^3 - F_G, L_G, \mathfrak{s}).
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Proof uses Honda-Kazez-Matić TQFT map on SFH:

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Theorem (Kálmán–M.)

$$c(\xi_{\mathfrak{s}})$$
 generates SFH($S^3 - F_G, L_G, \mathfrak{s}$).

Proof uses Honda–Kazez–Matić TQFT map on SFH:

 Each contact structure ξ_s on (S³ − F_G, L_G) includes into the standard tight contact structure on S³.

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Theorem (Kálmán–M.)

$$c(\xi_{\mathfrak{s}})$$
 generates $SFH(S^3 - F_G, L_G, \mathfrak{s})$.

Proof uses Honda–Kazez–Matić TQFT map on SFH:

- Each contact structure ξ_s on (S³ − F_G, L_G) includes into the standard tight contact structure on S³.
- Each ξ₅ is the complement of a neighbourhood of a Legendrian graph in S³.

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Thanks for listening!