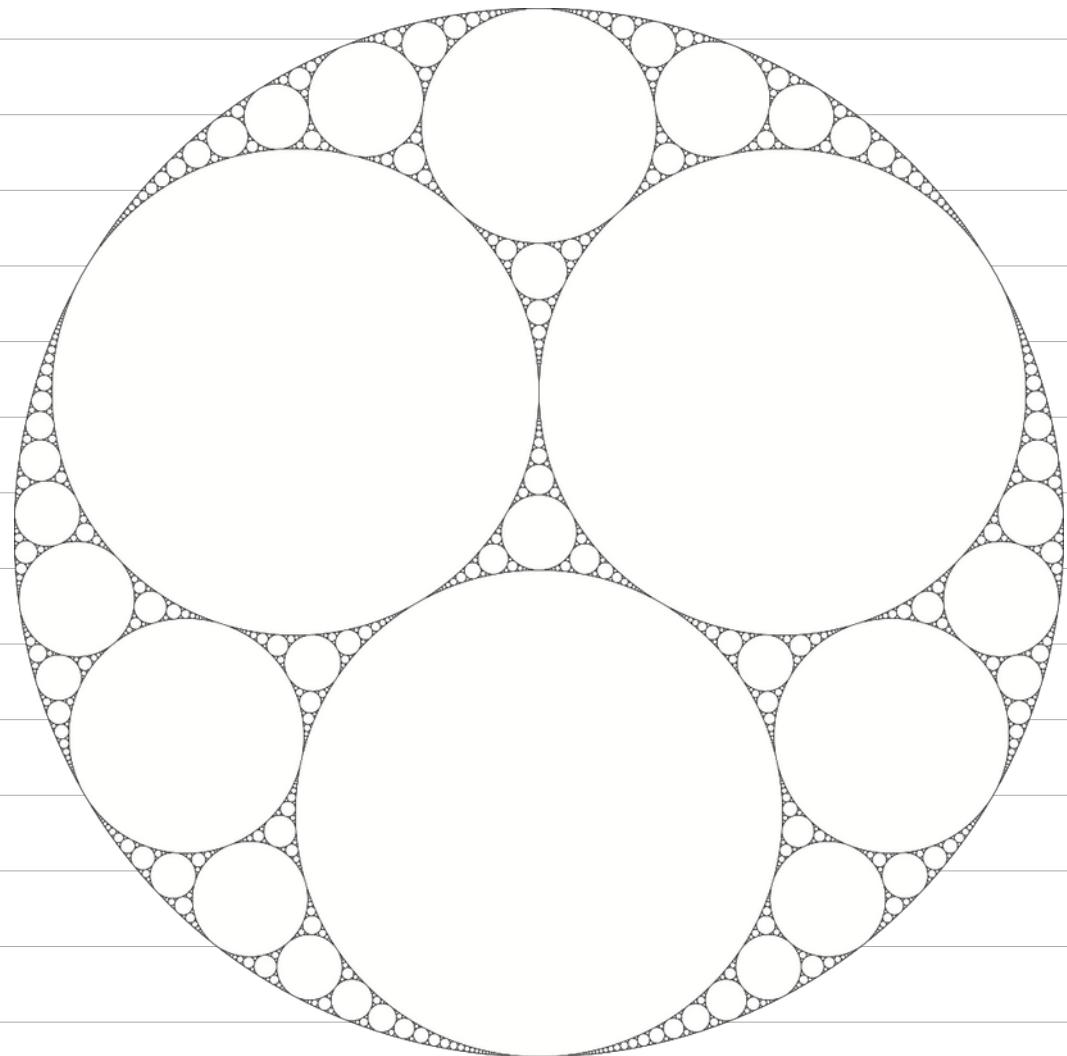


Circle Packings,
Lagrangian Grassmanns,
& Scattering Diagrams

Daniel Mathews

Monash topology seminar, 1/4/20



Overview

A few ideas from the theory of circle packings & recent work in progress
→ relations to spinors, symplectic geometry, Grassmannians & scattering theory.

- ① (Koebe, Andreev, Thurston, Stephenson, ...) There is a wonderful theory of packing circles in the plane
 - like "discrete complex analysis"
 - related to geometry of hyperbolic polyhedra (Purcell, Hodgson, ...)
- ② (M.) One can understand & compute circle packings (& more general arrangements) as Lagrangian plane arrangements in a symplectic and complex vector space of spinors.
- ③ (M.) The resulting mathematics is closely related to recent developments in $N=4$ susy Yang-Mills theory (on-shell diagrams, amplituhedron, ...).

(4)

(M) One can also understand & compute circle packings
via De Sitter geometry.

Highlights from the Theory of Circle Packings

Fix a 2-complex K , a triangulation of a surface (w/ or w/o ∂).

A collection of circles $\{C_v\}$ in a metric space is a circle packing for K if

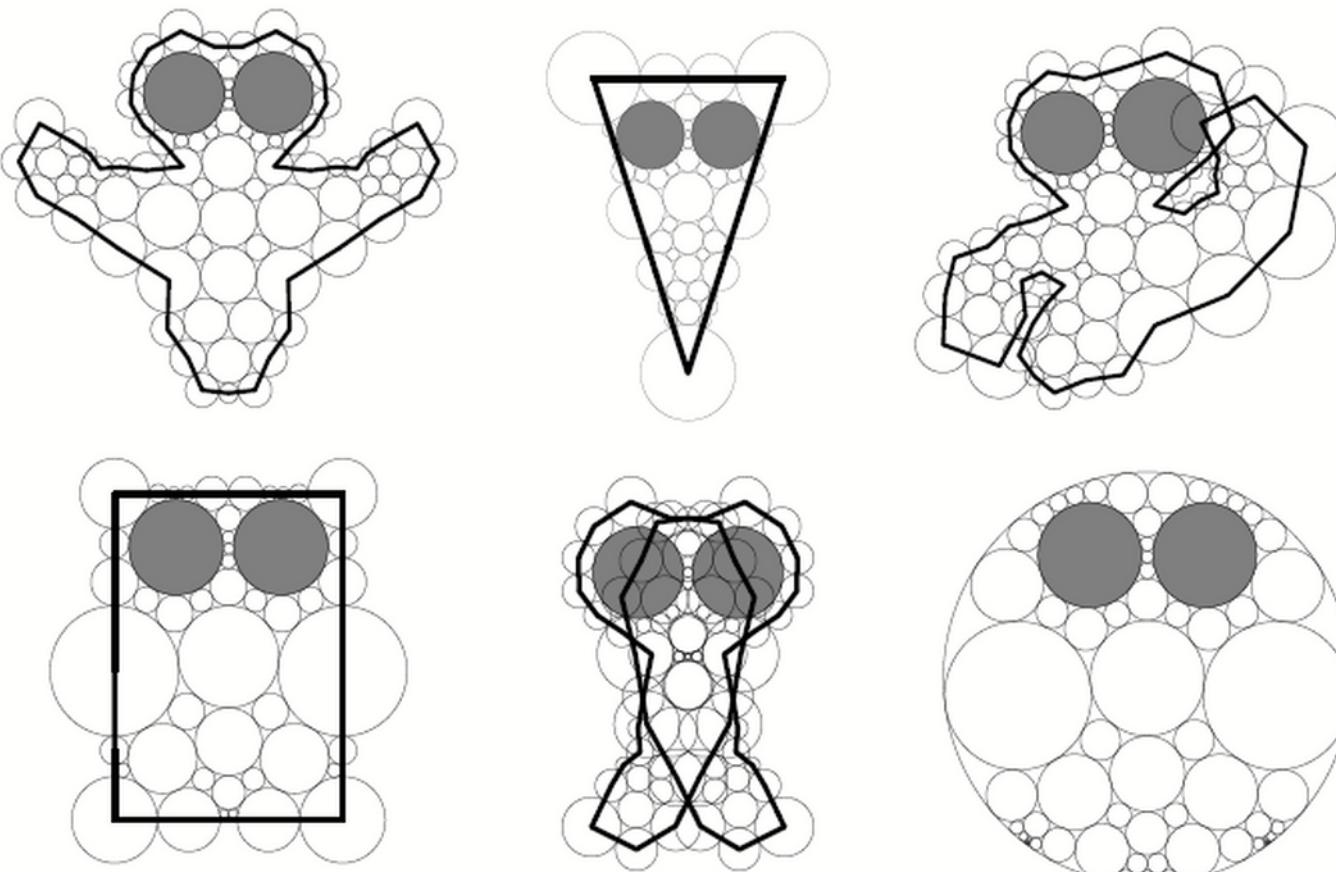
- (1) There is a circle C_v for each vertex v of K
- (2) C_u, C_v are externally tangent when u, v are joined by an edge
- (3) C_u, C_v, C_w form a positively oriented triple when u, v, w do.



Basically, you can always find a circle packing with spherical/Euclidean/hyp geometry.

Theorem: (Beardon-Stephenson 1990) If K is a disc then \exists a (locally univalent) Euclidean circle packing for K . Boundary radii can be prescribed arbitrarily!
It's unique up to Euclidean isometries.

Circle packings of a fixed triangulation K of a disc
with varying boundary radii.



Source: K. Stephenson, Circle packing & discrete analytic function theory

Spinors & Spacetime

Penrose, Rindler 1989: Think of spinors rather than tangent vectors on $S^2 \cong \mathbb{CP}^1$.

For present purposes, a spinor is just a vector in \mathbb{C}^2 .

A spinor $S = (w, z)$ has a spin vector, a tangent vector to \mathbb{CP}^1 given by the vector $\begin{pmatrix} 1 \\ w \end{pmatrix}$ at the point $\frac{z}{w}$.

Note: $re^{i\Theta} S$ has spin vector at the same point as S but its length is multiplied by r^2 and it's rotated by -2Θ .

There's an antisymmetric bilinear form $\{ \cdot, \cdot \} : \mathbb{C}^2 \otimes \mathbb{C}^2 \rightarrow \mathbb{C}$ on spinors given by $\{S_0, S_1\} = w_0 z_1 - z_0 w_1$.

Its imaginary part is a symplectic form ω on $\mathbb{C}^2 \cong \mathbb{R}^4$

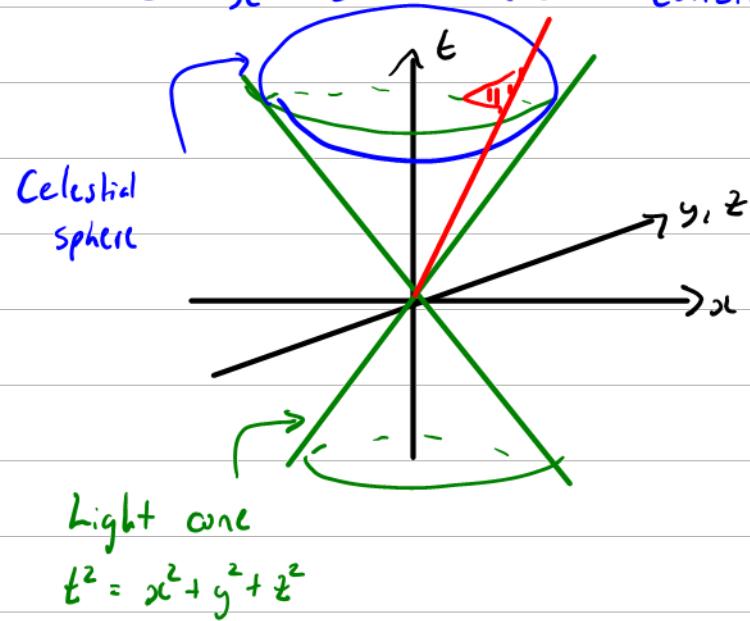
$$\omega : \mathbb{R}^4 \otimes \mathbb{R}^4 \rightarrow \mathbb{R}, \quad \omega(S_0, S_1) = \text{Im } \{S_0, S_1\}.$$

Are these really - spinors ?

Semi-Riemannian : for $v = (t, x, y, z)$,

$$\downarrow \quad \langle v, v \rangle = t^2 - x^2 - y^2 - z^2$$

Penrose & Rindler considered null vectors in Minkowski space. $\mathbb{R}^{3,1}$



Null lines through the origin, is along the light cone L
i.e. for which $dt^2 - dx^2 - dy^2 - dz^2 = 0$

are determined by their intersection with
the celestial sphere $L \cap \{t=1\}$
 $= \{ (x, y, z) : x^2 + y^2 + z^2 = 1 \}$
which is naturally regarded as $\mathbb{C}\mathbb{P}^1$.

Lorentz transformations of $\mathbb{R}^{3,1}$ effect Möbius transformations on $\mathbb{C}\mathbb{P}^1$
 $SO(3,1)^+ \cong PSL(2, \mathbb{C})$

Represent point of $\mathbb{C}\mathbb{P}^1$ as $[z:w] \cong \bar{z}/w$.

The redundancy in (z, w) gives a null flag — for us, a vector will do.

Spin vectors and Lagrangian subspaces

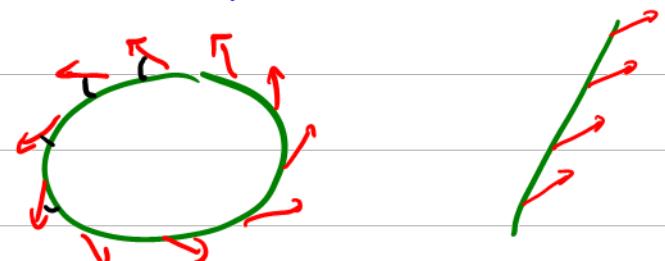
Let Π be a 2-(real)-dimensional subspace of \mathbb{C}^2 .

Facts (Penrose, Rindler): Let X denote the set of spin vectors of Π .

- * Π is complex \Leftrightarrow All vectors in X lie at a point
- * Otherwise, X consists of vectors along a circle in \mathbb{CP}^1 , making a constant angle.

* The spin vectors are tangent to the circle

$\Leftrightarrow \Pi$ is Lagrangian, i.e. ω vanishes on Π .



Indeed, there are natural bijections

Grassmannian $\text{Gr}(2,4) = \{2\text{-planes in } \mathbb{R}^4\} \longleftrightarrow \{\text{points and circles with directions in } \mathbb{CP}^1\}$

Lagrangian

$L\text{Gr}(2,4) = \{\text{Lagrangian 2-planes in } \mathbb{R}^4\}$

Grassmannian

$\longleftrightarrow \{\text{points and oriented circles in } \mathbb{CP}^1\}$

Lagrangian Plane Arrangements

Thus "Lagrangian planes have centres & radii" (= "distance from being complex")

Note: π Lagrangian $\Rightarrow i\pi$ Lagrangian
 \rightarrow Corresponds to reversing orientations of circles!

Statements about circle packings now translate into statements about Lagrangian planes
Ex -

Theorem (M): Suppose K triangulates a disc. Then \exists :

- * for each vertex v of K , a Lagrangian plane π_v
- * for each u, v connected by an edge, $\pi_u \wedge i\pi_v$ is 1-dimensional.
- * for each u, v, w around a positively oriented triangle,
 π_u, π_v, π_w have centres forming a positively oriented triangle.

Moreover, every boundary π_v can have any prescribed radius.

These planes are unique up to the action of $GL^+(2, \mathbb{C})$ on \mathbb{C}^2
(det real & positive)

Plücker Coordinates & Inversive Vectors

The Grassmannian $\text{Gr}(2,4)$ has projective Plücker coordinates

$$[\Delta_{12} : \Delta_{13} : \Delta_{14} : \Delta_{23} : \Delta_{24} : \Delta_{34}]$$

- * Given a 2-plane $\Pi \subset \mathbb{P}^4$, form a 2×4 matrix whose rows form a basis
- * Δ_{ij} = determinant of 2×2 submatrix formed by i^{th} & j^{th} columns

Lemma (M): For $\Pi \in \text{LGr}(2,4)$, its Plücker coordinates are

$$[K : -Kg + l : Kp : -Kp : -Kg - l : \tilde{K}]$$

where Π corresponds to a circle centred at $p+qi$ with curvature K (and $\tilde{K} = K(p^2+q^2) - \frac{l}{K}$)

Thus consider the vector $v_\Pi = (K, -Kg, Kp, \tilde{K})$ Inversive vector of Π .

Note

$$B \rightarrow \begin{bmatrix} K & -Kg & Kp & \tilde{K} \end{bmatrix} \begin{bmatrix} 1 \\ -2 \\ -2 \\ 1 \end{bmatrix} \begin{bmatrix} K \\ -Kg \\ Kp \\ \tilde{K} \end{bmatrix} = -2 \quad \text{so define a bilinear form} \cdot$$

$$\mathcal{J}(v, w) = v^T B w.$$

Circle Packing Equations

For any Lagrangian plane Π then $J(v_\Pi, v_\Pi) = -2$

But more...

Proposition (M, Lagarias - Mallows - Wilkes 2001) For Lagrangian Π, Π' corresponding to oriented circles C, C'

$$J(v_\Pi, v_{\Pi'}) = -2 \cos(\text{angle b/w } C, C') = \text{Inverse distance}(C, C')$$

So we obtain equations for tangency of circles! (or any prescribed angle!)

$$J(v, v) = -2 \text{ for each circle, } J(v, v') = 2 \text{ for tangency!}$$

One can find a circle packing for a triangulation K by solving quadratic equations of the form $J(v, w) = \pm 2$

~ Exercise in elimination theory

Generalisation of Descartes' Circle Theorem

Consider

$$K_n =$$



(n triangle around a central point)

A circle packing for K_n is a flower with n petals.

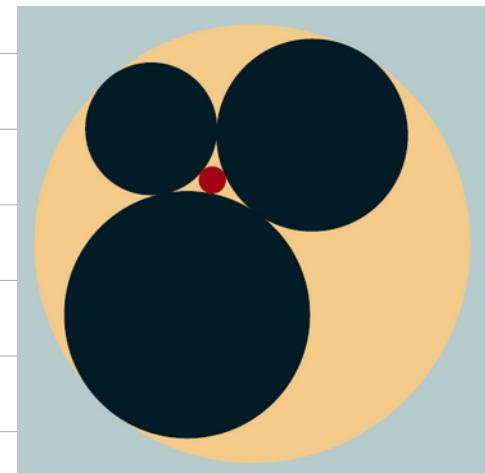
→ A central circle C_0 , surrounded by tangent circles C_1, \dots, C_n .

$n=3$: Flower = 4 mutually externally tangent circles.

Let k_i : curvature of C_i .

Descartes' Circle Theorem (1634):

$$(k_0 + k_1 + k_2 + k_3)^2 = 2(k_0^2 + k_1^2 + k_2^2 + k_3^2)$$



In general, circle packing theory says k_0 is a function of k_1, \dots, k_n .

Using our methods we can find generalisations for higher n .

$$\begin{aligned} \underline{n=4} \quad \text{Thm (M)} : & 16k_0^4 - 8k_0^2(k_1k_2 + k_2k_3 + k_3k_4 + k_4k_1 + 2k_1k_3 + 2k_1k_4) \\ & + (k_1^2 + k_2^2)(k_3^2 + k_4^2) - 16k_0k_1k_2k_3k_4 \left(\sum_{i=1}^4 \frac{1}{k_i} \right) - 12k_1k_2k_3k_4 = 0 \\ & - 2(k_1k_2 + k_3k_4)(k_2k_3 + k_4k_1) \end{aligned}$$

Source:
P Lervie

De Sitter Geometry

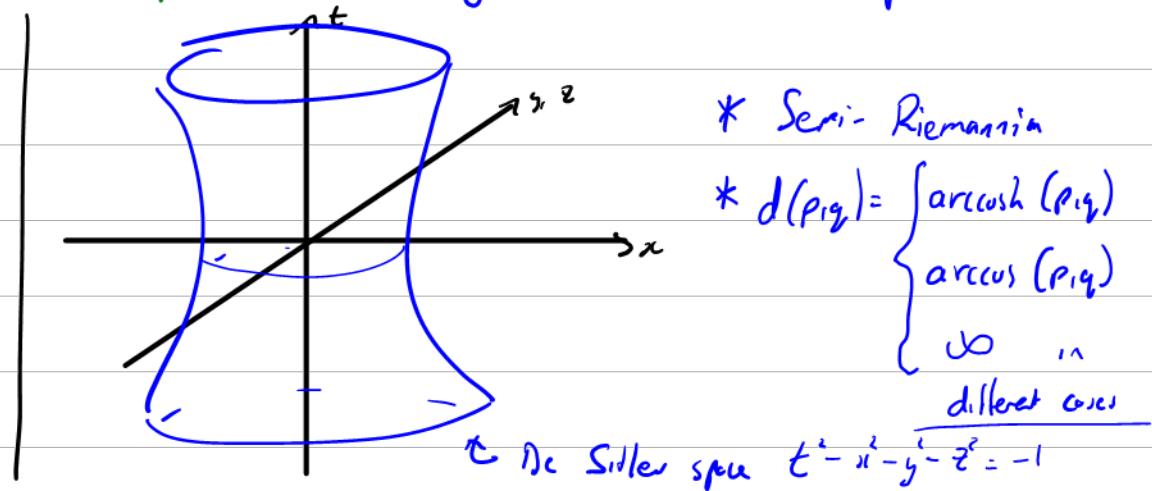
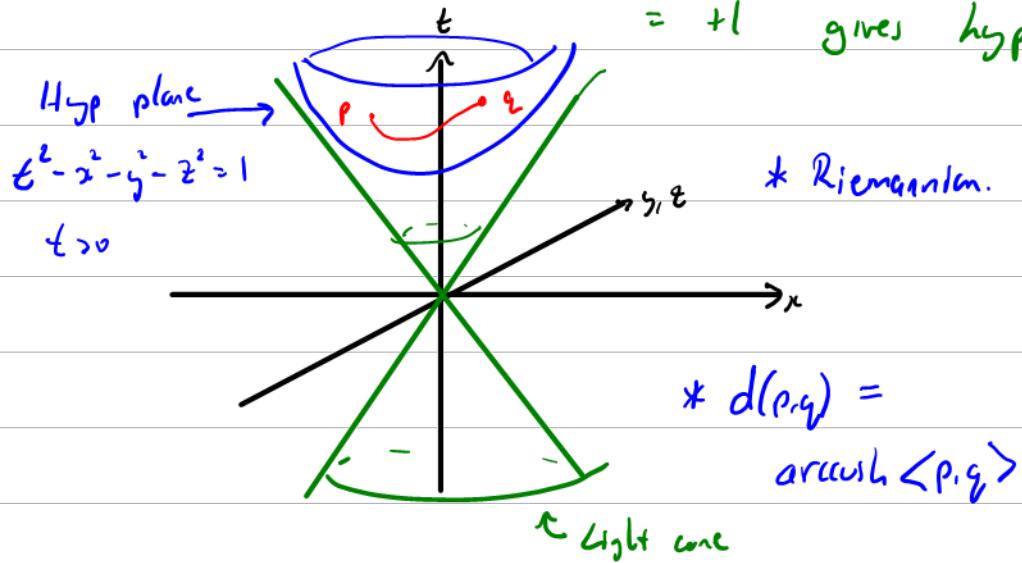
The quadratic form J has signature $(3,1)$ & in fact $J(v,v) = -2$ can be rewritten as

$$\left[\begin{array}{cccc} \frac{k+\tilde{k}}{2} & -Kg & Kp & \frac{\tilde{k}-k}{2} \\ 0 & " & " & " \\ \frac{k-\tilde{k}}{2} & x & y & z \end{array} \right] \begin{bmatrix} 1 \\ -1 \\ -1 \\ -1 \end{bmatrix} = \begin{bmatrix} \frac{k+\tilde{k}}{2} \\ -Kg \\ Kp \\ \frac{\tilde{k}-k}{2} \end{bmatrix} \quad \langle v, v \rangle = -1 \quad \text{in } \mathbb{R}^{3,1} !$$

$\Leftrightarrow t^2 - x^2 - y^2 - z^2 = -1 \dots$ So circles correspond to points in $\mathbb{R}^{3,1}$ with $\|p\| = -1$!

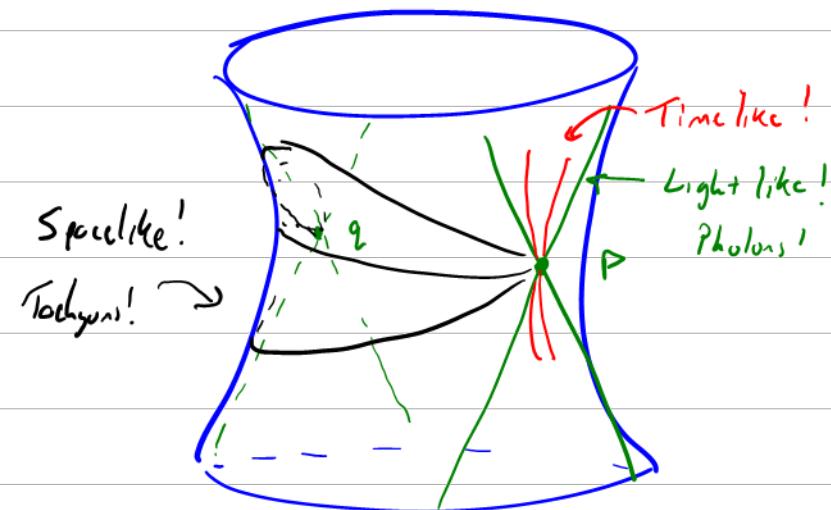
t
↑
 x y z

$= +1$ gives hyperbolic space, -1 gives de Sitter space!



Circle Packing as Extreme Physical Distancing

* From a point p in De Sitter space, there are geodesics to some but not all points.



* At p there is a light cone - lightlike geodesics from p .

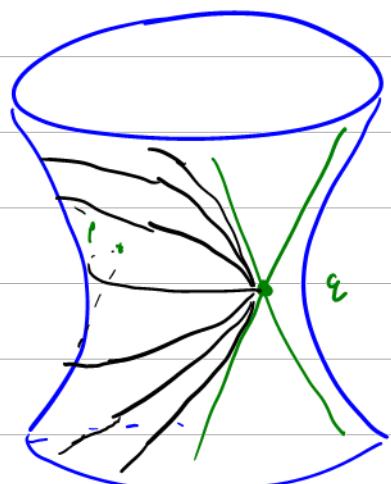
* p has an antipodal point q .

All spacelike geodesics from p go to q .

* Geodesics from p approach but cannot reach the light cone at q . \rightarrow The "horizon" of p .

Extremely separated from p !

Prop: $\langle p, p' \rangle = 1$ iff p' is on the horizon of p .

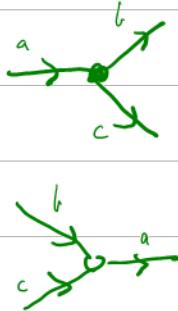
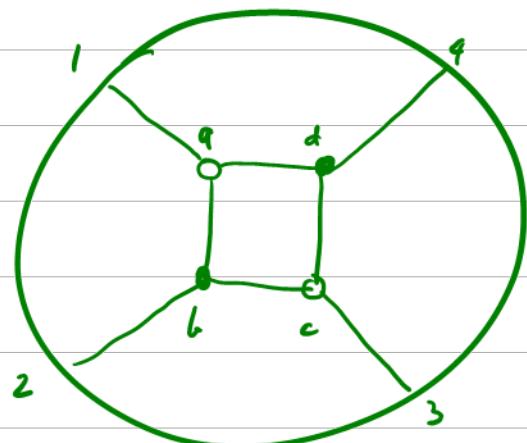


Circles with inverse vectors v, v' correspond to points $p, p' \in$ De Sitter. They are externally tangent iff $J(v, v') = 2$ iff $\langle p, p' \rangle = 2$
So...

Thm: A circle packing corresponds to an arrangement of points in De Sitter space where tangent circles correspond to extremely separated points!

Circle Packings as Scattering Diagrams

In the scattering theory of $N=9$ supersymmetric Yang-Mills theory, one considers "on-shell diagrams" which are planar bicoloured graphs with "external" vertices arranged in a circle. (A Postnikov, N Arkani-Hamed, many others...)



Each oriented edge E is decorated with a spinor \mathfrak{s}_E

At a black vertex, spinors are proportional
 $\mathfrak{s}_c = \alpha_c \mathfrak{s}_a, \quad \mathfrak{s}_b = \alpha_b \mathfrak{s}_a$

At a white vertex, two spinors sum to the third
 $\mathfrak{s}_a = \mathfrak{s}_b + \mathfrak{s}_c$.

Find space of solutions to these equations given "external" spinors.

Given "external" spinors, solve for others in terms of parameters α_e .

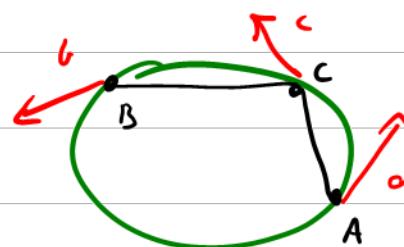
The space of solutions, with positivity conditions, is a polytope from which one can find scattering amplitudes as a volume - "amplituhedron"

On-shell Diagrams are Circle Diagrams



Certain quantities in scattering theory then have an interpretation in Euclidean geometry!

Edge parameters \sim ratios
 α_a, α_b



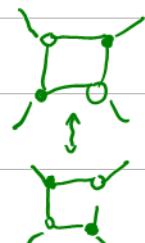
$$\frac{C-B}{C-A} = \frac{\alpha_b}{\alpha_a}$$

Face parameters \rightarrow Generalised cross-ratio

(\prod edge parameters around a face)



$$\frac{C-B}{C-A} \cdot \frac{D-A}{D-B}$$



Cluster transformations \rightarrow Cross-ratio transformations!

Ptolemy relation \rightarrow Ptolemy's theorem for cyclic quadrilaterals!