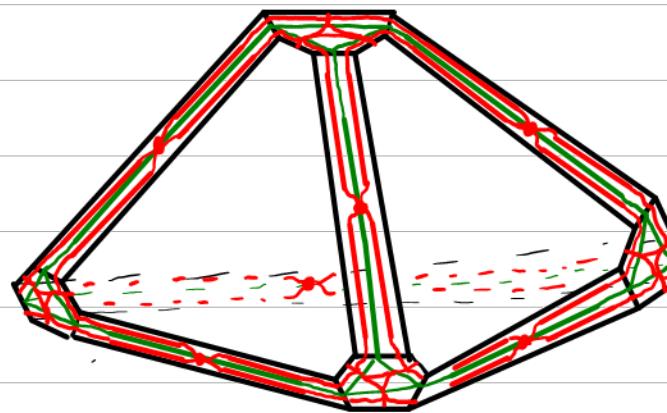
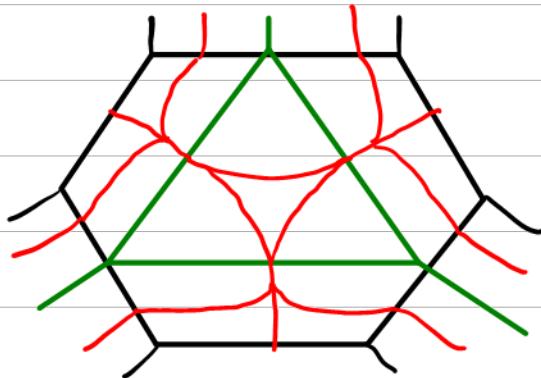


A Symplectic Basis

for

3-manifold triangulations



Daniel. Mathews © monash.edu

AustMS Annual Meeting

8/12/21

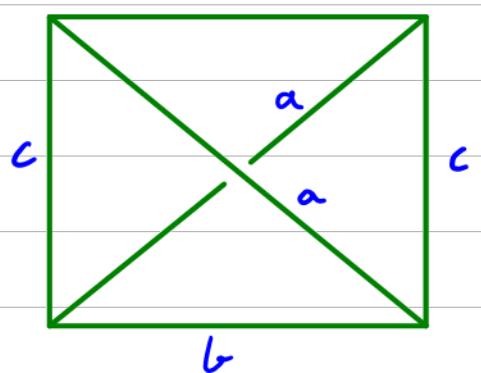
joint work with Jessica Purcell

Combinatorics of 3-manifold Triangulations

Let: $* M$ be a knot/link complement, $M = S^3 \setminus L$

* Γ an ideal triangulation of M
 with tetrahedra $\Delta_1, \Delta_2, \dots, \Delta_N$
 and edges E_1, E_2, \dots, E_N

Label opposite pairs of edges of each Δ_j with a, b, c as shown



The incidence matrix of Γ
 is the $N \times 3N$ matrix

(Sparse! Each entry 0, 1 or 2!
 Columns sum to 2!)

Let $a_{k,j} = \# a\text{-edges of } \Delta_j \text{ identified to } E_k$
 $b_{k,j} = \# b\text{-edges of } \Delta_j \text{ identified to } E_k$
 $c_{k,j} = \# c\text{-edges of } \Delta_j \text{ identified to } E_k$

$$I_n = E_1 \begin{bmatrix} a_{11} & b_{11} & c_{11} & a_{12} & b_{12} & c_{12} & \cdots & a_{1N} & b_{1N} & c_{1N} \end{bmatrix}$$

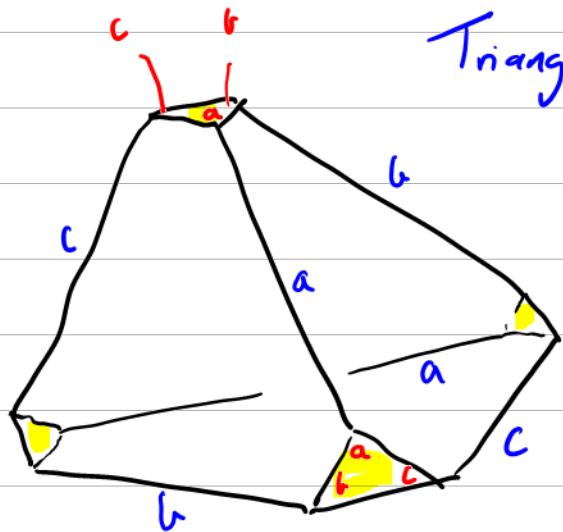
$$E_2 \begin{bmatrix} a_{21} & b_{21} & c_{21} & a_{22} & b_{22} & c_{22} & \cdots & a_{2N} & b_{2N} & c_{2N} \end{bmatrix}$$

$$\vdots \quad \vdots \quad \vdots \quad \ddots \quad \vdots$$

$$E_N \begin{bmatrix} a_{N1} & b_{N1} & c_{N1} & - & - & - & \cdots & a_{NN} & b_{NN} & c_{NN} \end{bmatrix}$$

Boundary Combinatorics of 3-manifold Triangulations

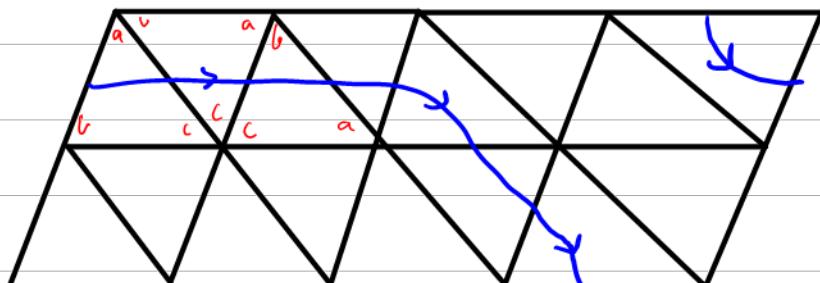
Truncating each Δ_j gives a decomposition of a compact manifold $\bar{M} = S^3 \setminus N(L)$ into truncated tetrahedra!



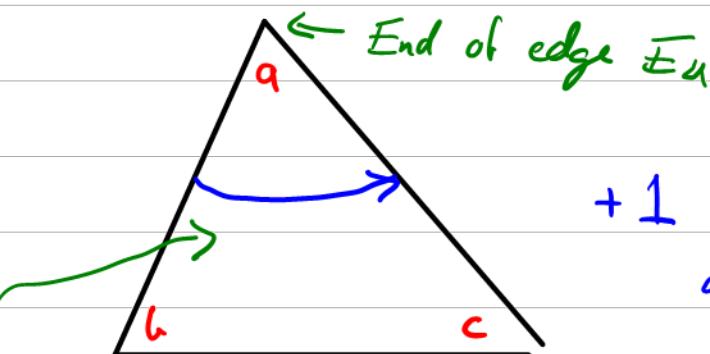
Triangular faces give a triangulation of the boundary tori!

Each vertex of each triangle has an a, b, c label!

A generic curve γ in a boundary torus then has a combinatorial holonomy $\tilde{h}(\gamma) \in \mathbb{R}^{3n}$



Triangle from Δ_j



+1 to a_j coordinate!

Neumann - Zagier matrix

Reduce! From the $N \times 3N$ incidence matrix $I_N = [a_{kj} \ b_{kj} \ c_{kj}]$

to an $N \times 2N$ matrix with entries $[a_{kj} - c_{kj} \ b_{kj} - c_{kj}]$

Add! For each boundary torus T_i take a meridian m_i , longitude l_i :

We can naturally add $\tilde{h}(m_i), \tilde{h}(l_i)$ rows (in \mathbb{R}^{3N}) to I_N
 & reduce them to give rows of length $2N$, $h(m_i), h(l_i) \in \mathbb{R}^{2N}$

The result: the Neumann - Zagier matrix!

$$NZ = \left\{ \begin{array}{c} \text{Edges} \\ \vdots \\ E_1 \\ E_2 \\ \vdots \\ E_N \end{array} \right\} \underbrace{\begin{bmatrix} a_{11}-c_{11} & b_{11}-c_{11} & \cdots & a_{NN}-c_{NN} & b_{NN}-c_{NN} \\ \vdots & \ddots & \ddots & \vdots & \vdots \\ a_{N1}-c_{N1} & b_{N1}-c_{N1} & \cdots & a_{NN}-c_{NN} & b_{NN}-c_{NN} \end{bmatrix}}_{\text{Tetrahedra}} = \left\{ \begin{array}{c} R_1 \\ R_2 \\ \vdots \\ R_N \\ R_1^m \\ R_1^e \end{array} \right\}$$

$$\left\{ \begin{array}{c} m_1 \\ l_1 \end{array} \right\} \xrightarrow{\quad h(m_1) \quad} \xrightarrow{\quad h(l_1) \quad}$$

Properties of the NZ matrix

Let V be a $2N$ -dimensional vector space generated by $3N$ elements

$$a_1, b_1, c_1, \dots, a_N, b_N, c_N$$

subject to relations $a_i + b_i + c_i = 0$

Regard the row space of I_n as \mathbb{R}^{3N}
and the row space of NZ as V ! }
So rows $R_k, R_k^m, R_k^\ell \in V$

Defn: There is a natural symplectic form ω on V given by

(antisymmetric
nondegenerate
bilinear)

$$\omega(a_i, b_i) = \omega(b_i, c_i) = \omega(c_i, a_i) = 1$$

$$\omega(b_i, a_i) = \omega(c_i, b_i) = \omega(a_i, c_i) = -1$$

$$\text{& } \omega \text{ on all other pairs of generators} = 0$$

Theorem (NZ 1985):

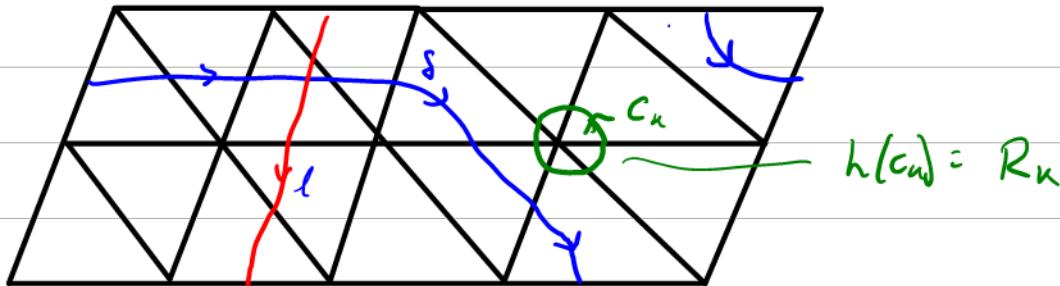
All rows of NZ are ω -orthogonal except $\omega(R_k^m, R_k^\ell) = 2$.

Geometric meaning of the NZ theorem

NZ showed in fact that for curves on boundary tori,
 ω gives algebraic intersection number

$$\omega(h(\gamma), h(\delta)) = 2 \cdot \gamma \cdot \delta.$$

Edge rows R_K can be interpreted as holonomy around an edge of T



However, NZ showed that
 $\text{rank}(NZ) = N + N_c < 2N$
So $R(NZ) \subsetneq V$

Qn: Can we give a geometric interpretation for V , ω more generally?

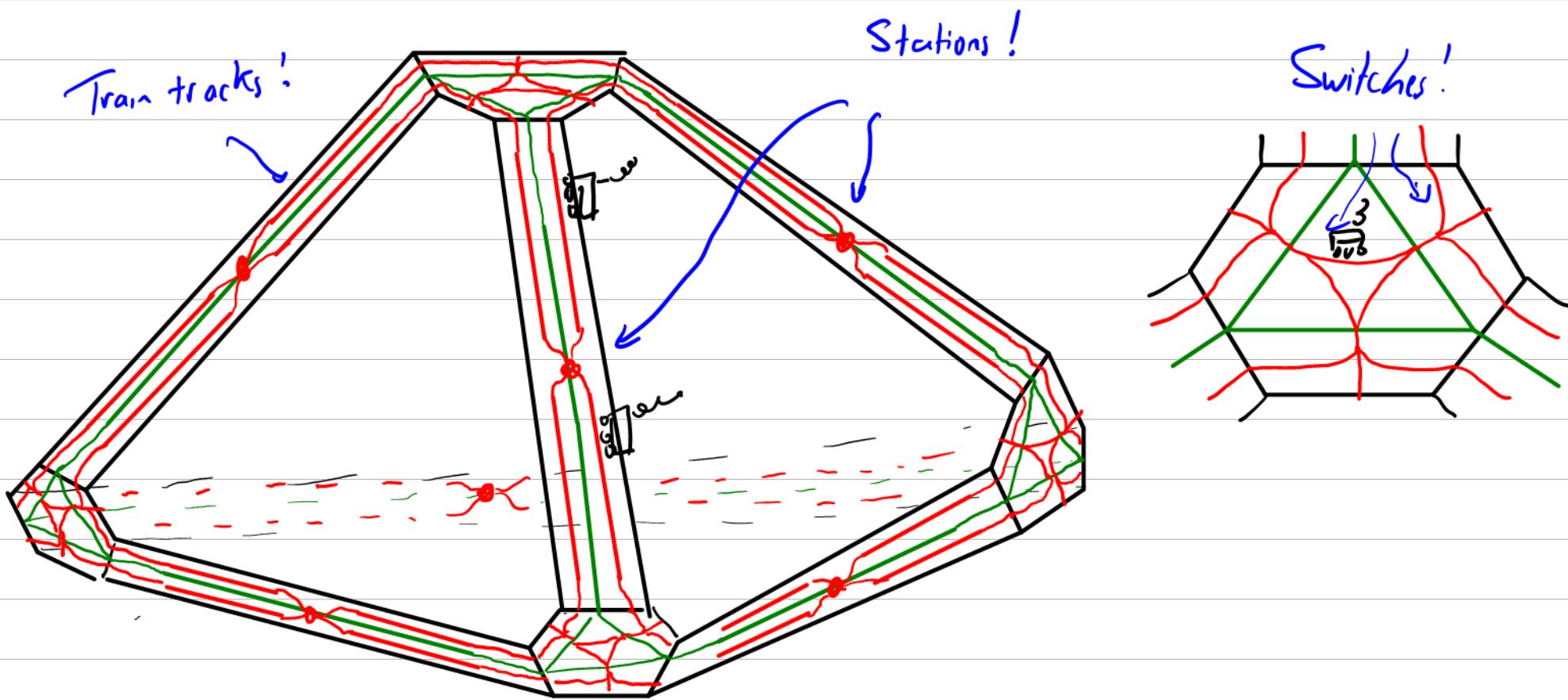
Dimovte (2013): By adding rows, NZ can be made into a symplectic matrix.
But many choices ... what to choose?

Also .. Isn't this supposed to be 3 dimensional?

All aboard!

Welcome to the

M-Purcell 3-manifold train track transport system!



Oscillating Curves

From the triangulation \mathcal{T} , truncate tetrahedra as before.

Now also remove a neighbourhood of each edge

→ Heegaard decomposition of M

$M = \text{Handlebody} \cup \text{Compression Body},$

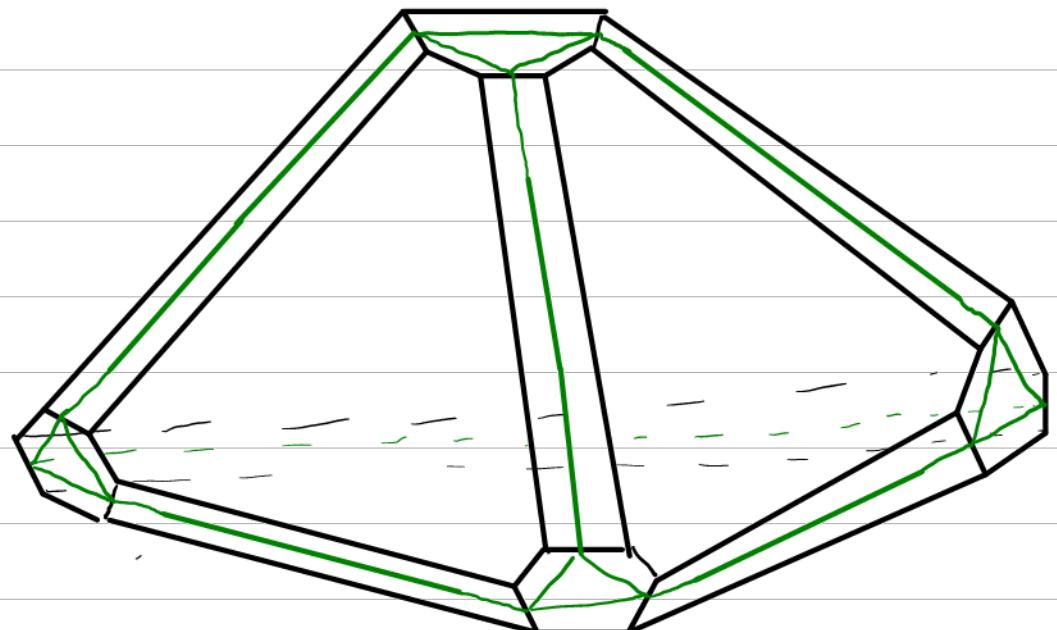
with handlebody decomposed into polyhedra

The Heegaard surface is decomposed into rectangles & triangles

We place a system of train tracks on them!



when you pass through a station you must
(?!)



Geometric meaning & symplectic basis

Defn: An oscillating curve \mathcal{S} on T is a smooth closed curve train journey, reversing orientation at stations.

(This means you must pass through an even number of stations!)

The segments of \mathcal{S} along triangles have a, b, c labels
→ \mathcal{S} has a combinatorial holonomy $h(\mathcal{S}) \in V$.

Theorem (M-Purcell) For any oscillating curves $\mathcal{S}, \mathcal{S}'$:

$$w(h(\mathcal{S}), h(\mathcal{S}')) = 2 \underbrace{\mathcal{S} \cdot \mathcal{S}'}_{\text{Intersection number on Heegaard surface.}}$$

Corollary: By choosing oscillating curves \mathcal{S}_k "dual" to the curves C_k around edges
 $\mathcal{S}_k \cdot C_k = \delta_{kk}$

we obtain a symplectic basis of V

Example: Figure 8 knot

